

Proof Complexity using structured circuits

TU Ilmenau

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Joint work with Christoph Berkholz.

Introduction

Input: CNF $\varphi = \bigwedge_{i \in [m]} C_i$

Goal: Prove that φ is unsatisfiable

C_1

C_2

C_3

\dots

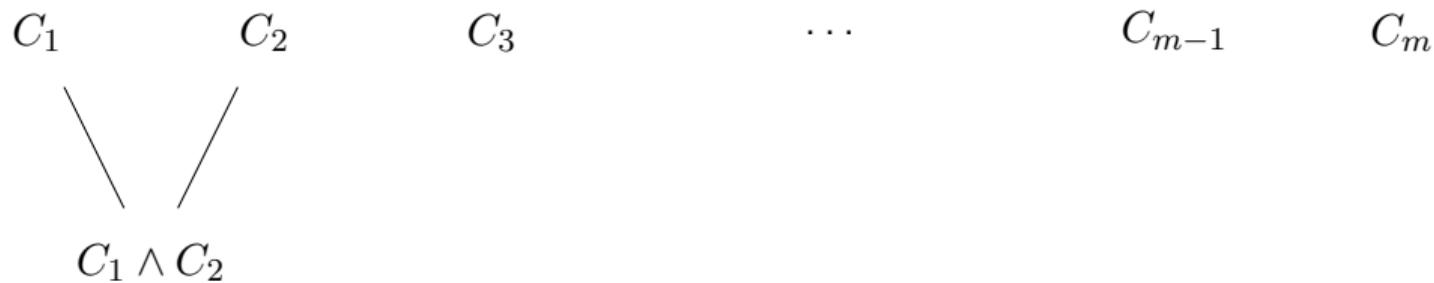
C_{m-1}

C_m

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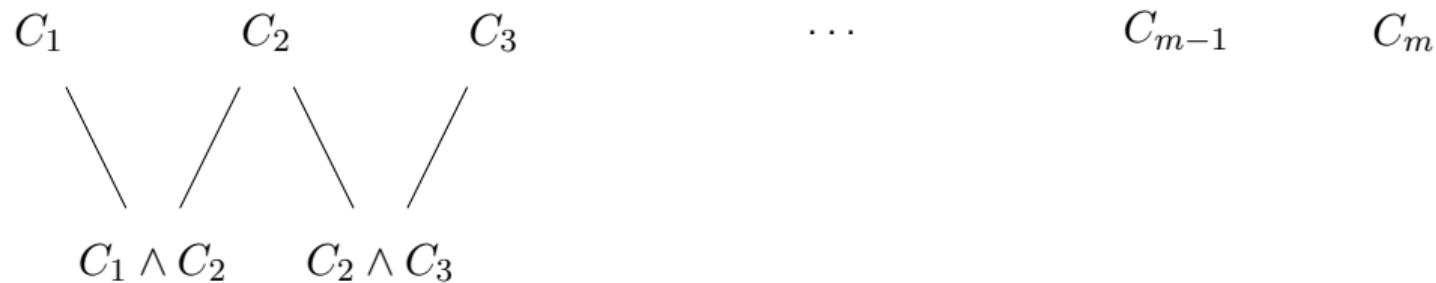
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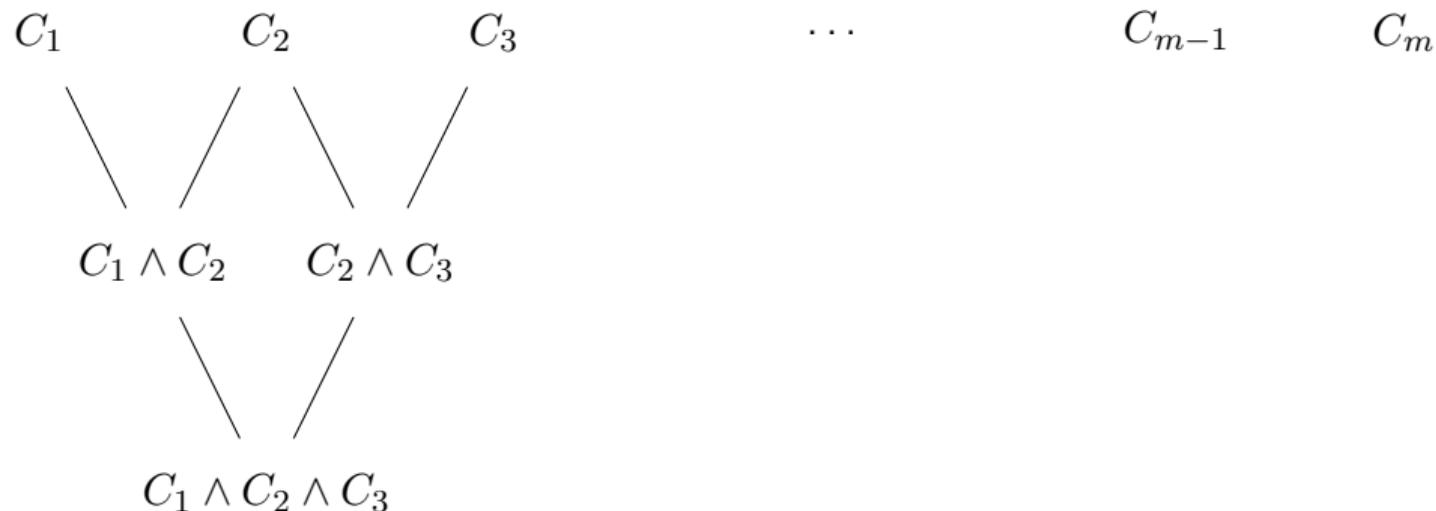
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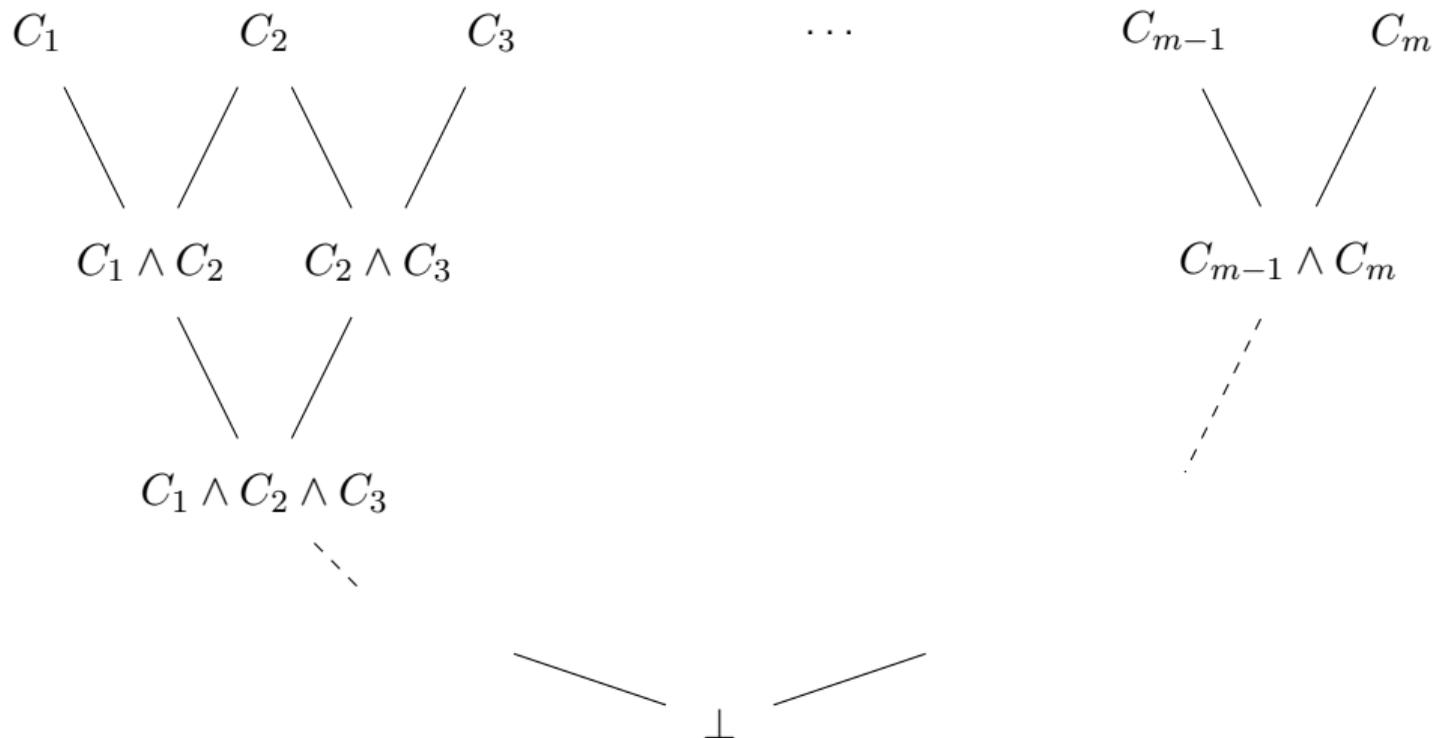
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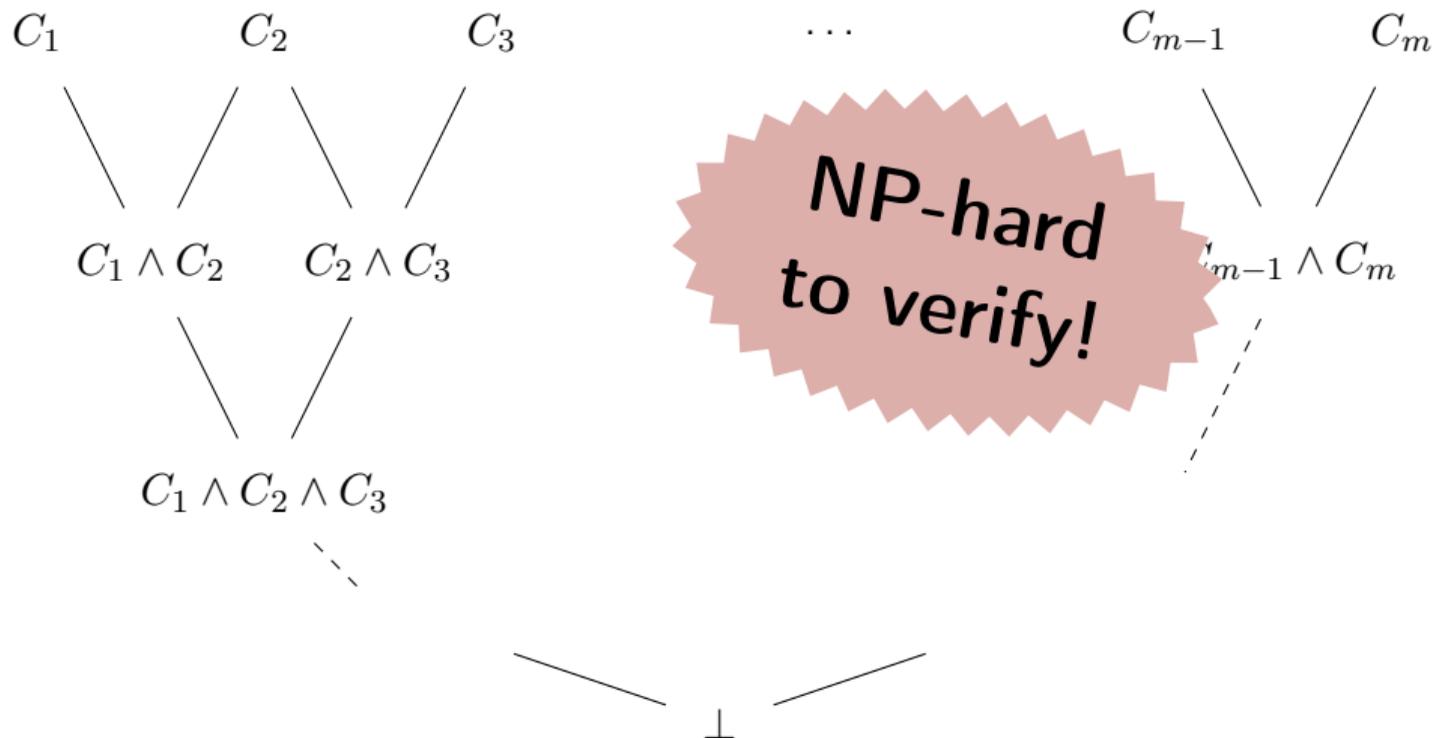
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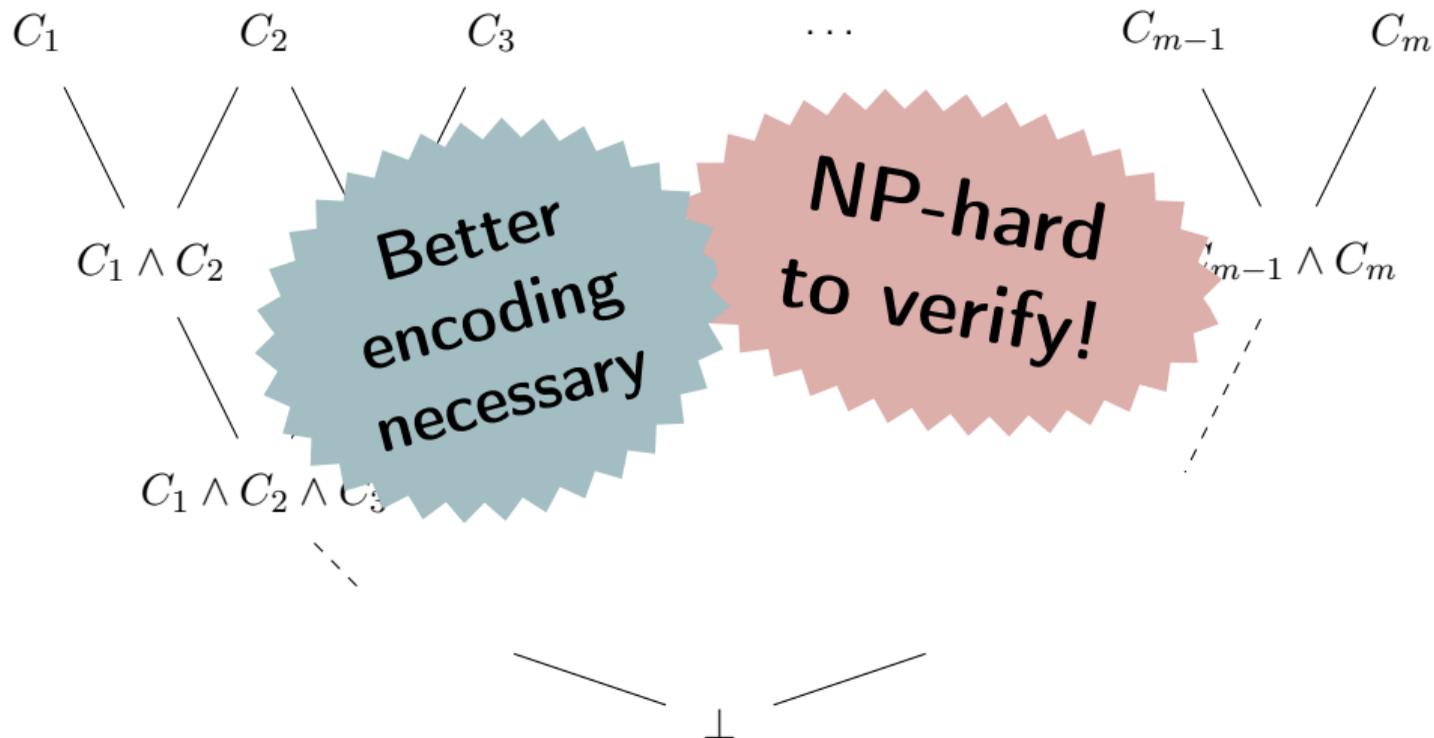
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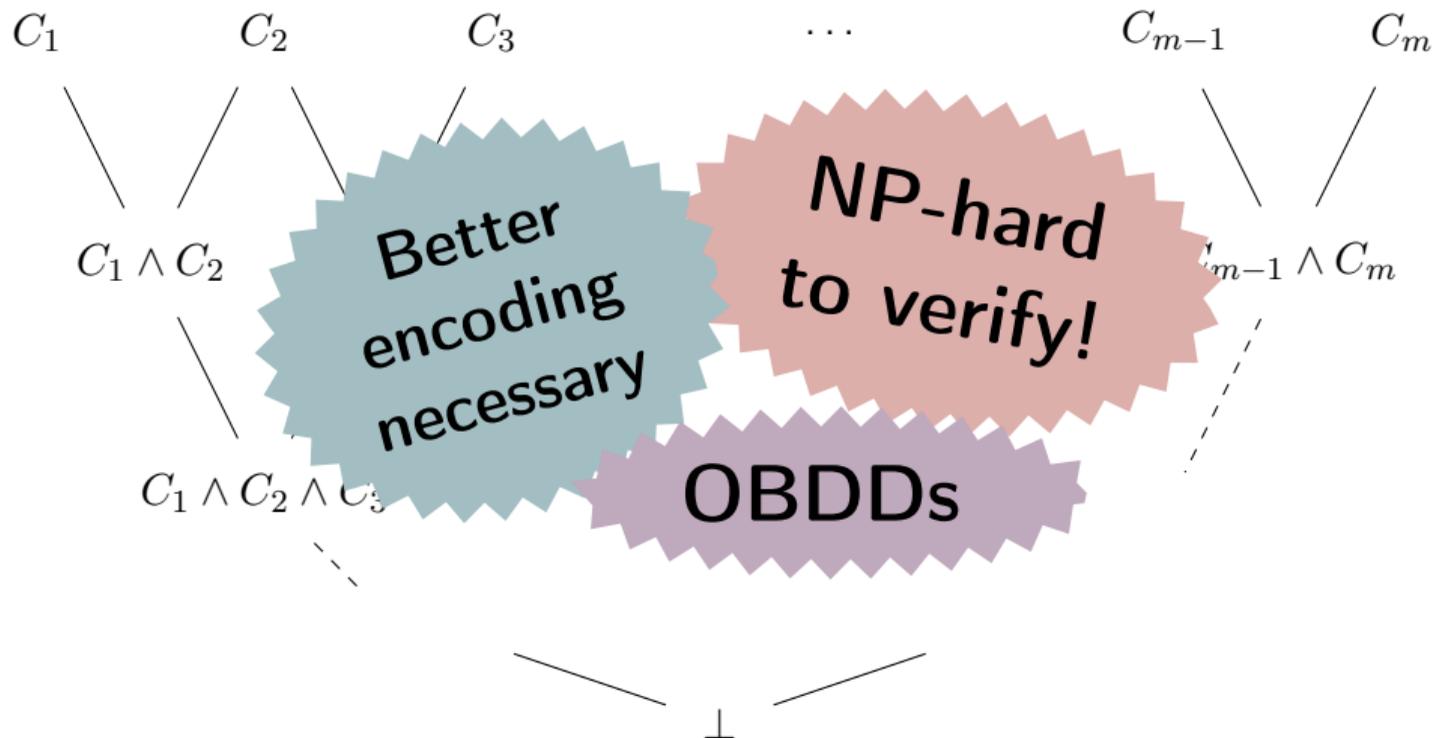
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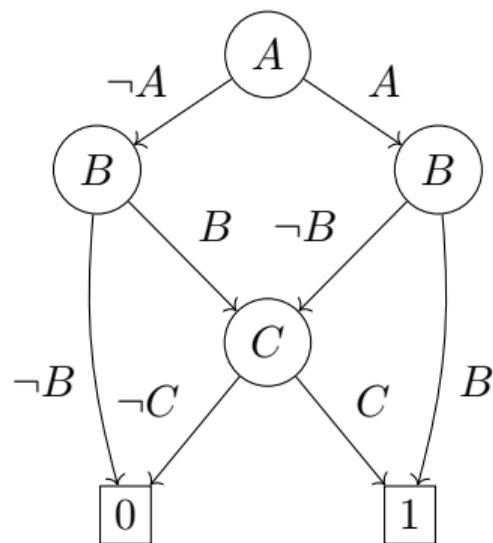
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Ordered Binary Decision Diagram

Ordered Binary Decision Diagram (OBDD):

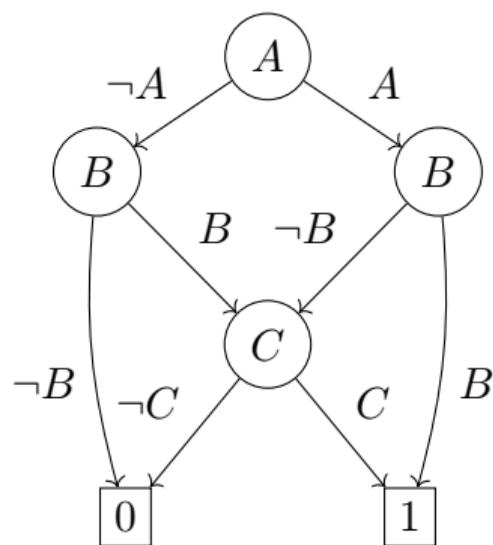


An OBDD for $(A \wedge B) \vee (A \wedge C) \vee (B \wedge C)$

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- Support polynomial satisfiability checking
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 - size of $D_1 \wedge D_2$ is in $\mathcal{O}(|D_1| \cdot |D_2|)$
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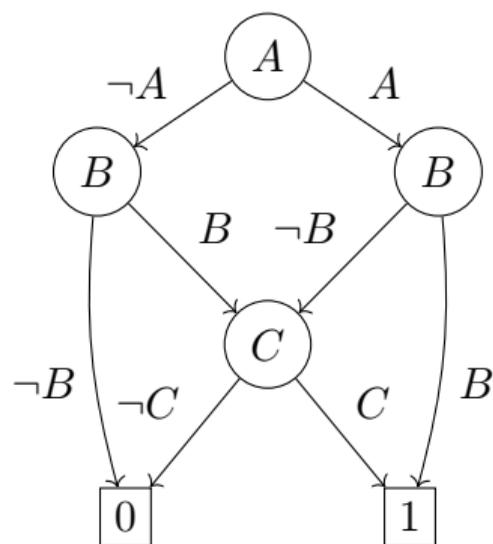


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- Downside: Many Boolean functions do not have small OBDDs



An OBDD for $(A \wedge B) \vee (A \wedge C) \vee (B \wedge C)$

OBDD-based proof systems

Proof as a sequence of OBDDs

Let $\varphi := \bigwedge_{i \in [m]} C_i$ be a CNF

- init: construct D_i equivalent to some clause C_j
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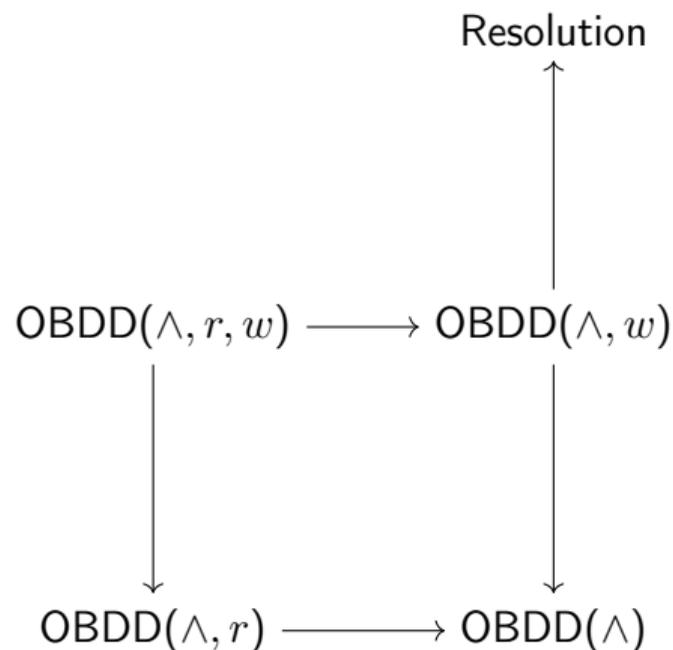
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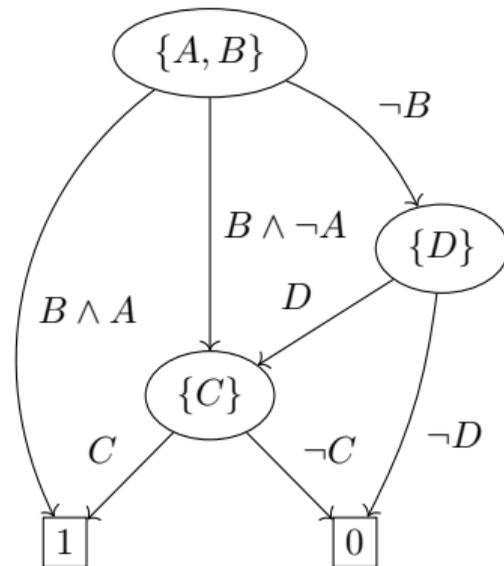
p-simulation: Every Proof in system A of length ℓ can be transformed into a proof in system B of length $p(\ell)$



Sentential Decision Diagrams

Sentential Decision Diagram (SDD):

- decide on multiple variables at once
 - ▶ decisions have to partition all possible assignments
 - ▶ Each decision represented as another SDD



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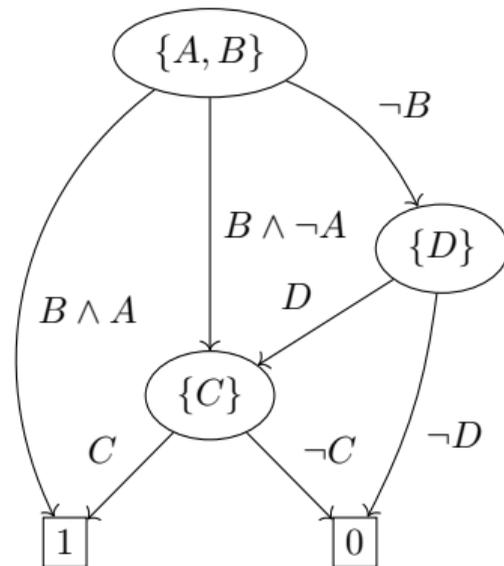
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Can also be viewed as a circuit. Decisions take the form

$$\bigvee (f_i \wedge g_i)$$

such that

- each f_i and g_i are again SDDs deciding on disjoint variable sets X_f and X_g
- the models of all f_i form a partition of $\{0, 1\}^{X_f}$



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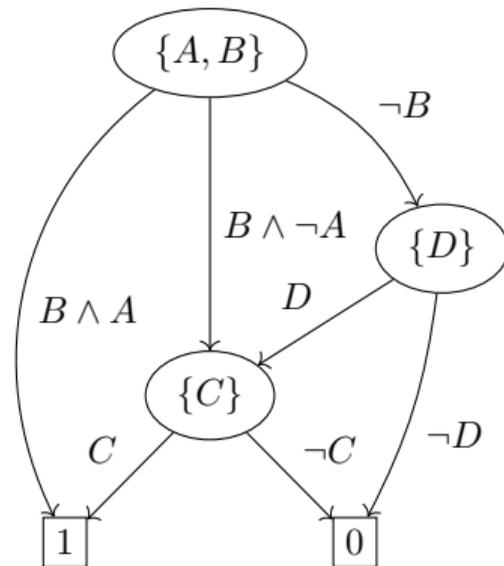
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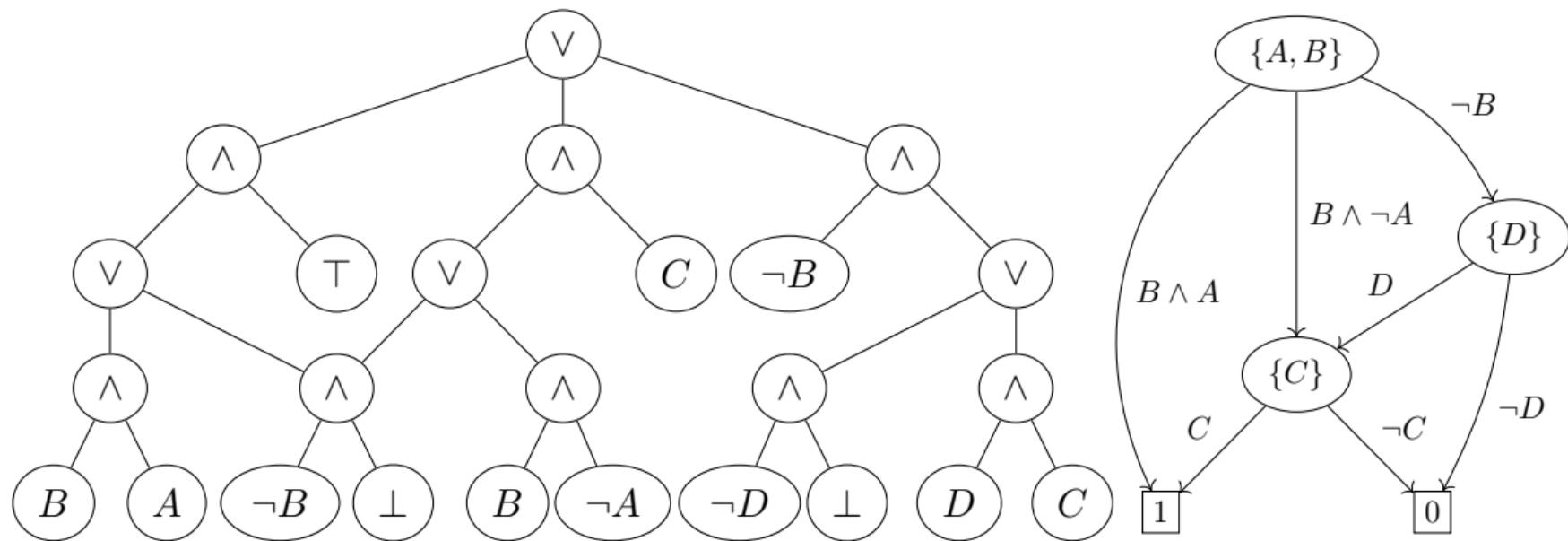
Linear order not good enough for these decisions

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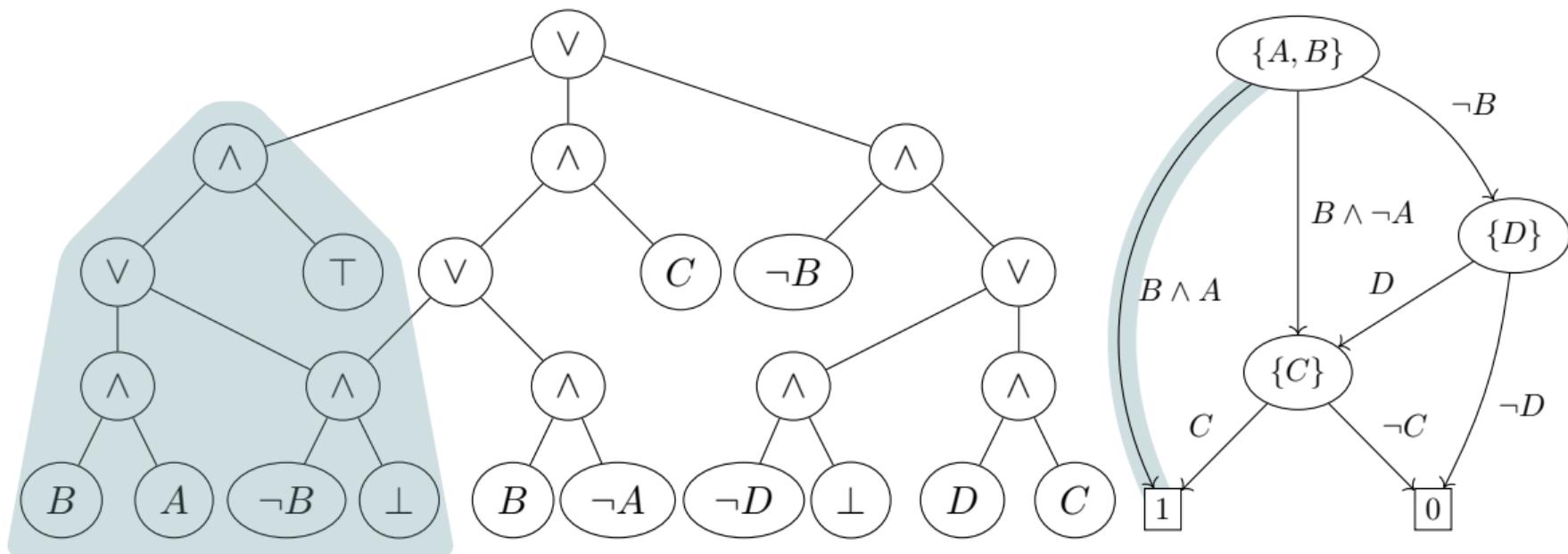
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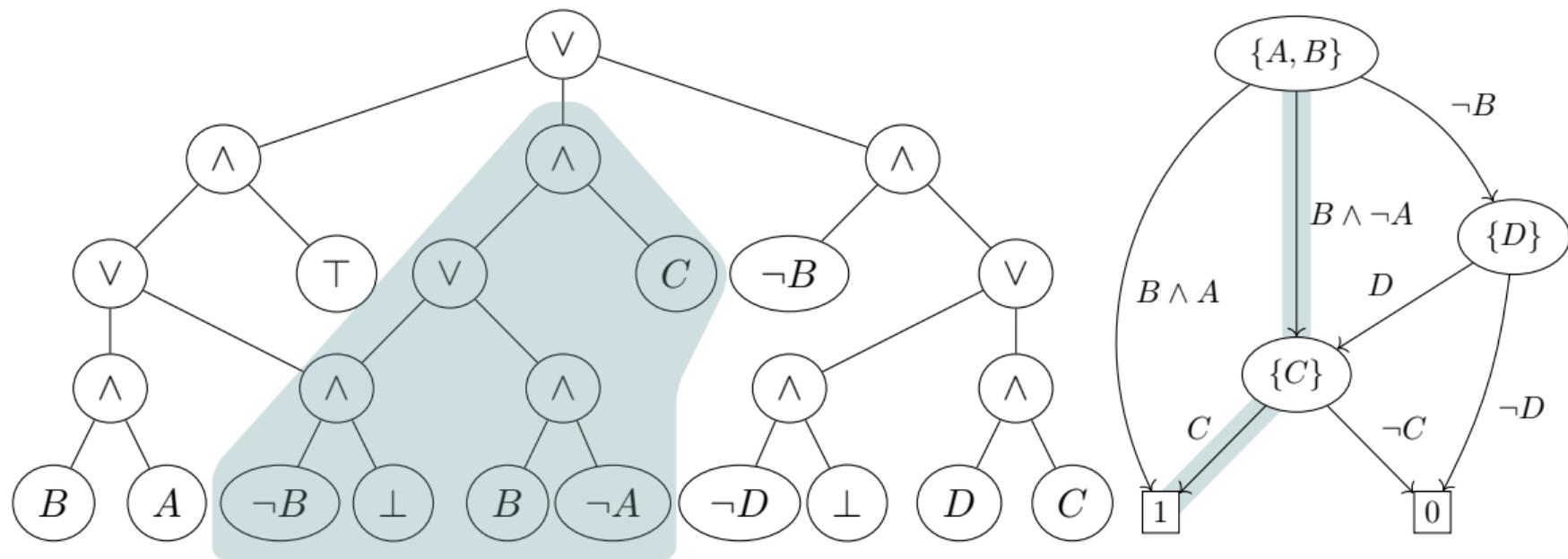
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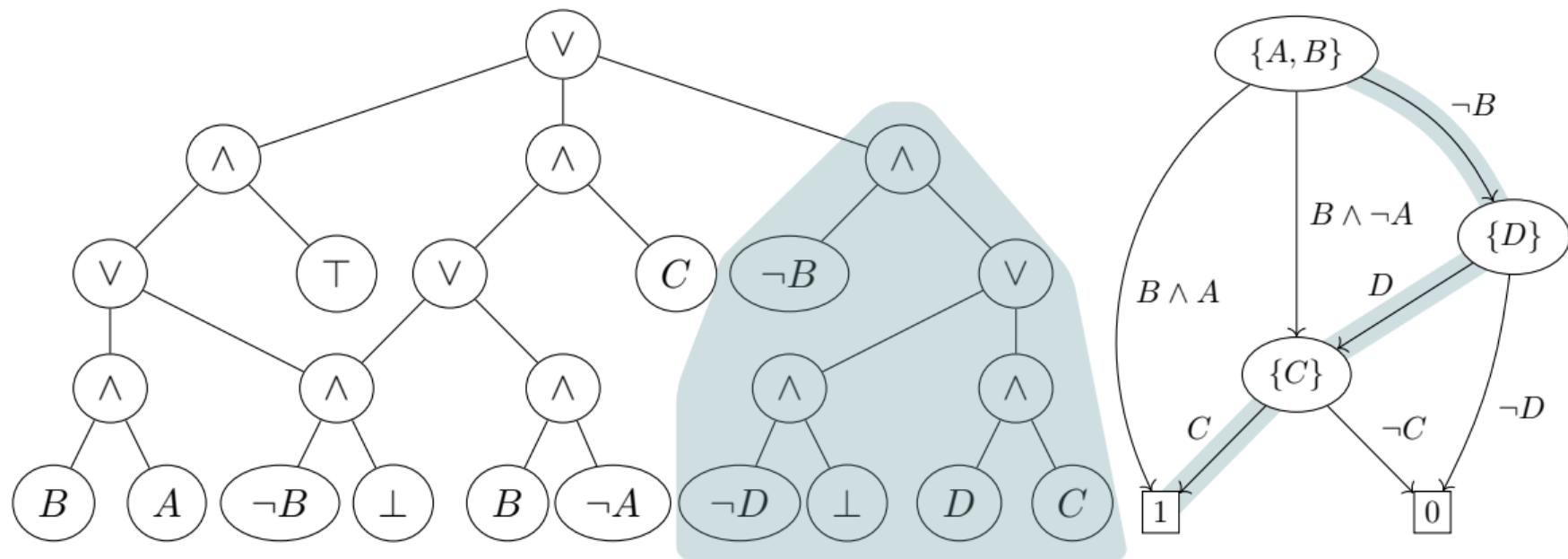
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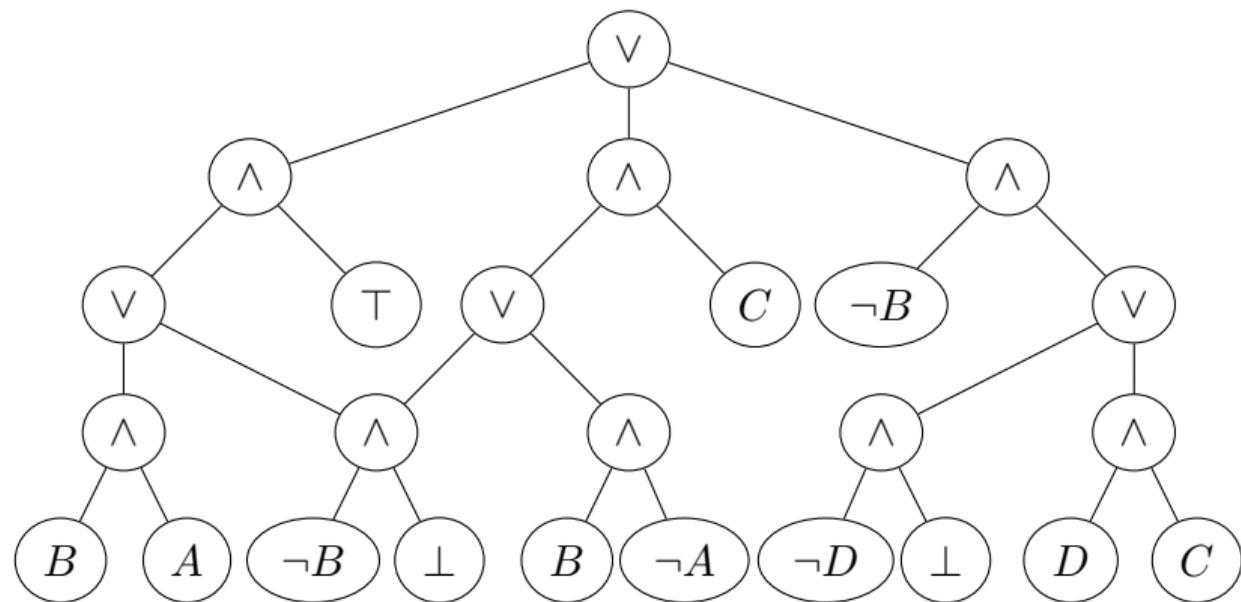
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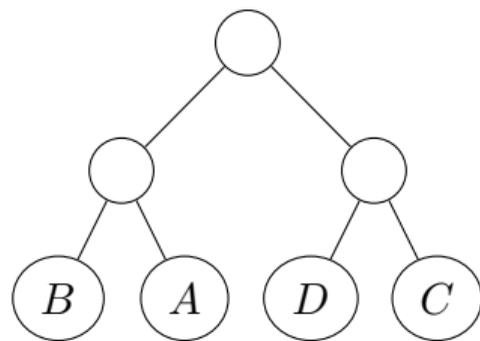
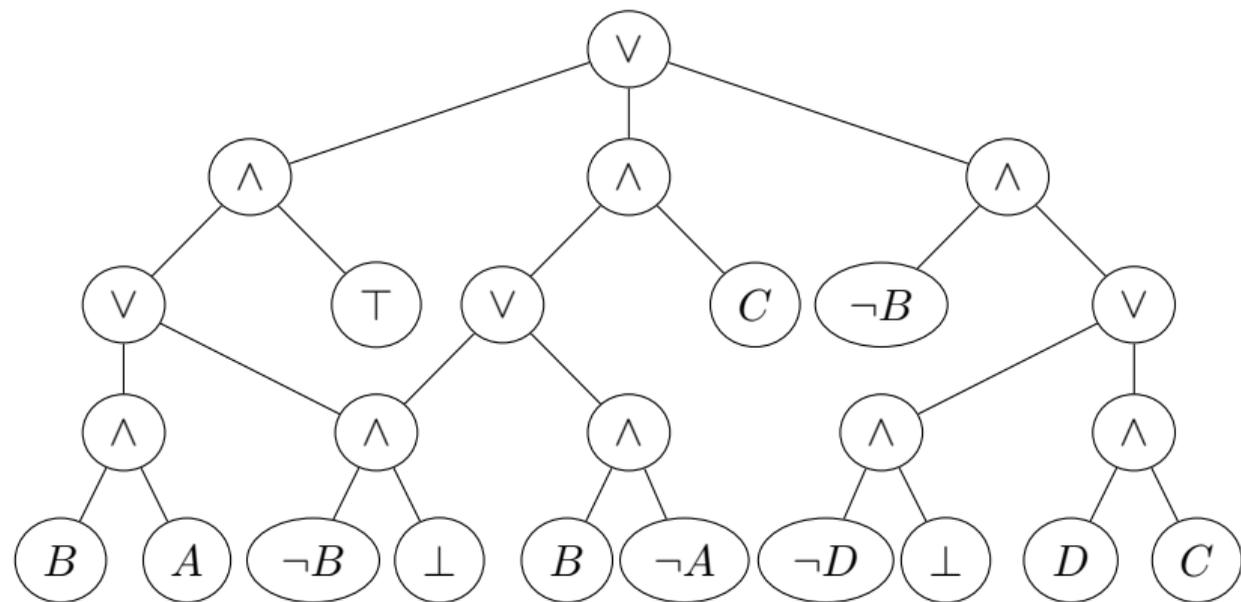
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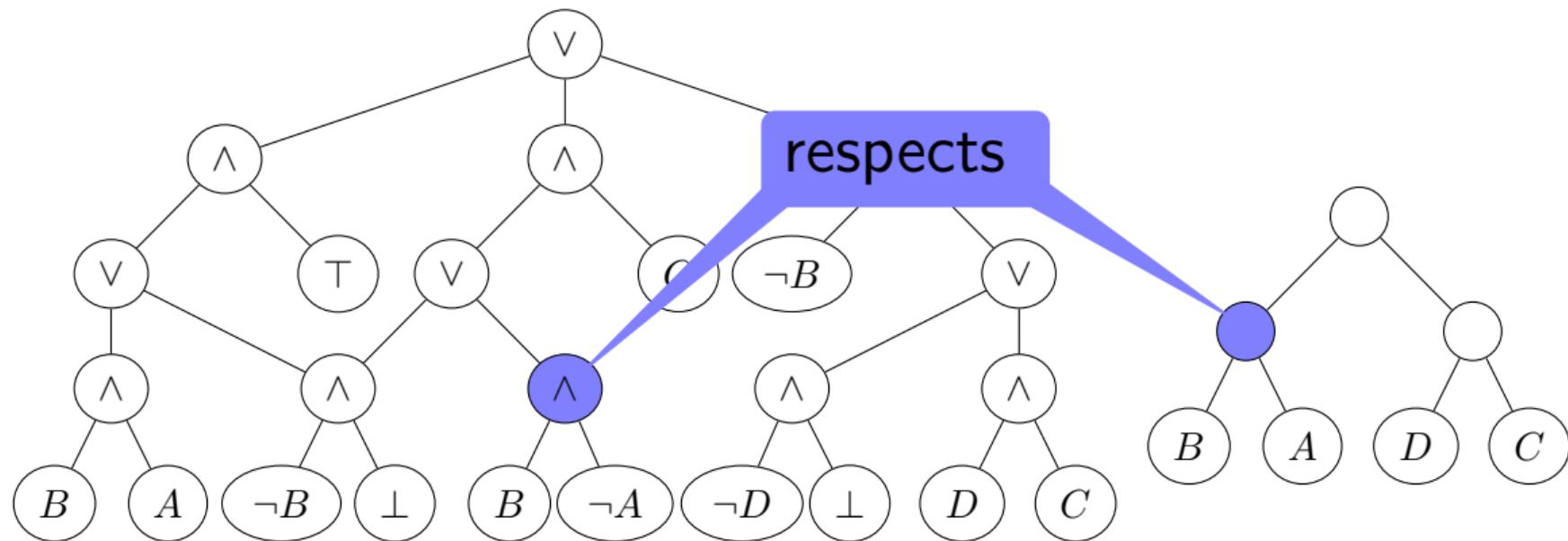
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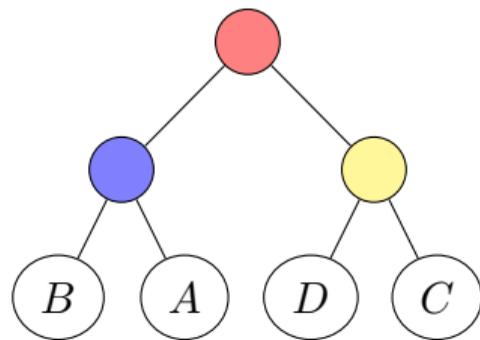
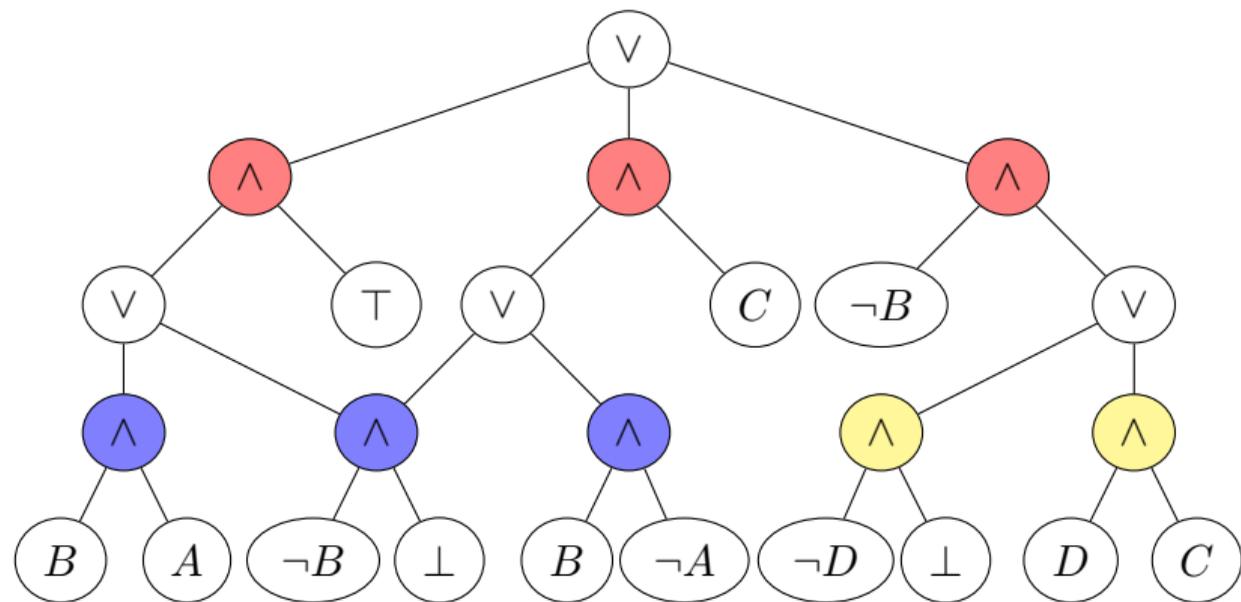
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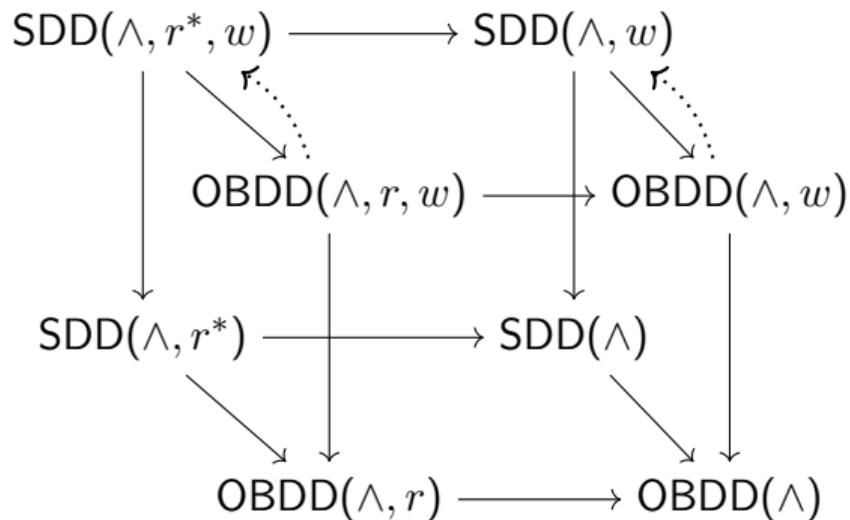


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Our results

Support the the following polynomial-time operations

- Satisfiability checking
- Conjunction (respecting the same vtree)
- Weakening (respecting the same vtree)



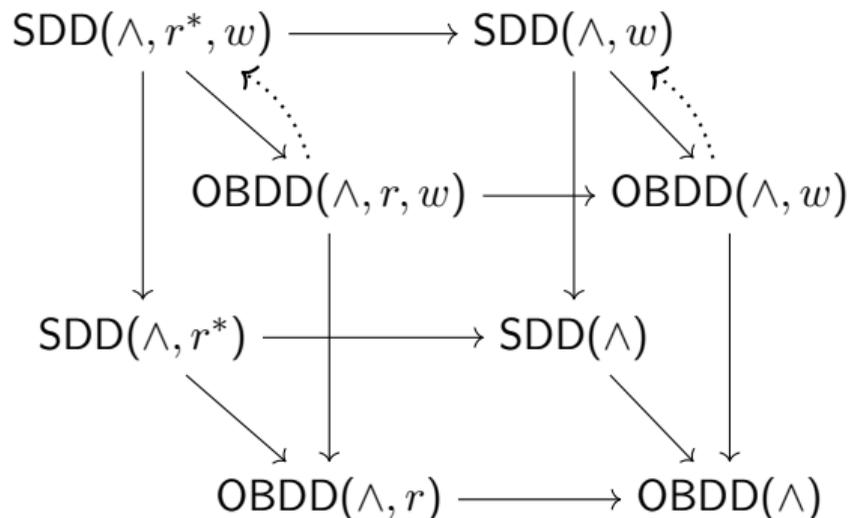
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- Exponentially more succinct than OBDDs
- Can represent any CNF φ in size $\mathcal{O}(n \cdot 2^{\text{tw}(\varphi)})$



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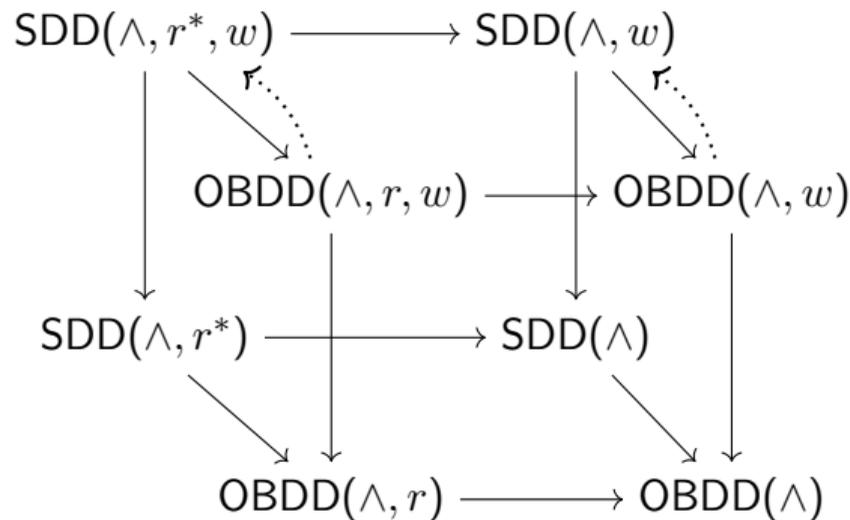
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Unknown whether SDDs support polynomial-time restructuring (r)

→ Use restricted restructuring (r^*) instead



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However: There are many superpolynomial separations for satisfiable formulas

- Lift knowledge compilation lower bounds to proof Complexity
- Make satisfiable CNFs unsatisfiable
- Ideally works on many CNFs
- Ideally works on many different representation formats

Making CNFs unsatisfiable

Definition ($\mathcal{Z}(\varphi)$)

Let $\varphi := \bigwedge_{i \in [m]} C_i$ be a CNF. We define

$$\mathcal{Z}(\varphi) = \varphi \wedge \bigwedge_{i \in [m]} (C_i \rightarrow (z_i \rightarrow z_{i+1})) \wedge z_1 \wedge \neg z_{m+1}$$

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For every satisfiable φ the transformed $\mathcal{Z}(\varphi)$ is unsatisfiable

φ is called *reduced* if it does not contain unnecessary clauses or literals

→ For every reduced CNF φ , the transformed $\mathcal{Z}(\varphi)$ is *minimally* unsatisfiable

Lower bounds for $\mathcal{Z}(\varphi)$

φ is a *monotone* (k, ℓ) -CNF, if

- Every literal only appears positively
- Every clause contains k literals
- Every variable appears in at most ℓ clauses

Let $G = (V, E)$ be a graph of maximal degree Δ . Then

$$\text{VC}(G) = \bigwedge_{\{u,v\} \in E} (u \vee v)$$

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Theorem

Let φ be a reduced monotone $(k, \sqrt{\log n})$ -CNF, $\mathfrak{C} \in \{\text{OBDD}, \text{SDD}\}$, and R_1, \dots, R_ℓ be $\mathfrak{C}(\wedge, r)$ -refutation of $\mathcal{Z}(\varphi)$ of size $t(n)$.

Then there is a \mathfrak{C} -representation of φ of size $\mathcal{O}(t(n)^2 \cdot n^{k^2})$.

Proof (Sketch)

Let $D_1 \wedge D_2 = \perp$ be the last step of the refutation

Goal: find partial assignments a_1, a_2 and a poly-sized D^* such that

$$D_1|_{a_1} \wedge D_2|_{a_2} \wedge D^* \equiv \varphi$$

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Goal: define α_i such that $D_1|_{\alpha_1} \wedge D_2|_{\alpha_2}$ is a sub-CNF of φ

- Do not leave “broken” clauses
- Do not remove too many clauses

Proof (cont.)

Assume $C_1 \in \varphi$, and let $\mathcal{U}_1 := \perp_{\text{var}(C_1)}$.

Because φ is reduced, it holds that

- $D_1|_{\mathcal{U}_1}$ is satisfiable, but
- $\mathcal{U}_1 \models \neg C_1$

Therefore, $D_1|_{\mathcal{U}_1}$ “breaks” the implication chain at the clauses of $C_1 \rightarrow (z_i \rightarrow z_{i+1})$

$$\perp_X : X \rightarrow \{0, 1\}$$

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$$z_1 \longrightarrow z_2 \longrightarrow \dots \longrightarrow z_i \longrightarrow z_{i+1} \longrightarrow \dots \longrightarrow z_{m-1} \longrightarrow z_m$$

Proof (cont.)

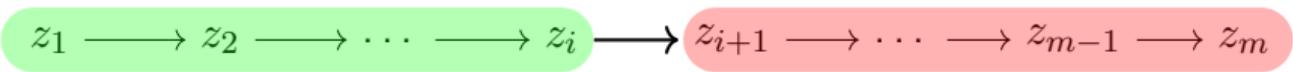
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This allows us to assign all z -variables without any contradiction

→ let \mathcal{d} be such an assignment to the z -variables

It remains to show that we did not remove too many clauses

Proof (cont.)

Let $\mathcal{C} := \{C_j \setminus C_1 \mid C_j \cap C_1 \neq \emptyset\}$ the set of *broken clauses*

Let c_1 be a minimal model of \mathcal{C} and $a_1 := b_1 \cup c_1 \cup d$

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Let D^* be the OBDD (SDD) collecting all clauses satisfied by either a_i

→ $|D^*| \in \mathcal{O}\left(2^{k^2 \cdot \log n}\right) = \mathcal{O}\left(n^{k^2}\right)$

→ $D_1|_{a_1} \wedge D_2|_{a_2} \wedge D^* = \varphi$

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→ $D_1|_{a_1} \wedge D_2|_{a_2} \wedge D^* = \varphi$

Therefore, $|D_\varphi|$ bounded in $\mathcal{O}\left(|D_1| \cdot |D_2| \cdot |D^*| = t(n)^2 n^{k^2}\right)$

Separation Example

Known superpolynomial lower bounds on φ imply superpolynomial lower bounds on $\mathcal{Z}(\varphi)$

Lemma (Razgon (2014))

For every $k > 50$ there is a class $\mathcal{G} := (G_i)_{i \in \mathbb{N}}$ of constant degree graphs s.t. for every $G_n \in \mathcal{G}$

- $tw(G_n) = k$ and $|V(G_n)| \in \mathcal{O}(n)$
- Every OBDD representing $VC(G_n)$ has size $n^{\Omega(k)}$

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- Every OBDD representing $VC(G_n)$ has size $n^{\Omega(k)}$

Consequence: Every OBDD(\wedge, r)-refutation of $\mathcal{Z}(VC(G_n))$ has size $n^{\Omega(k)}$

Separation Example

Known superpolynomial lower bounds on φ imply superpolynomial lower bounds on $\mathcal{Z}(\varphi)$

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→ Quasipolynomial separation between OBDD(\wedge, r) and SDD(\wedge)

Outlook

It is possible to further generalise our results

- Our main method also works for CNF classes beyond monotone $(k, \sqrt{\log n})$ -CNFs
 - Potential exponential separation between $\text{OBDD}(\wedge, r)$ and $\text{SDD}(\wedge)$
- Lifting method also works on classes beyond OBDD and SDD (e.g. structured-d-DNNF)

Unfortunately, weakening can easily refute every $\mathcal{Z}(\varphi)$

- More tools necessary to separate $\text{OBDD}(\wedge, w)$ and $\text{SDD}(\wedge, w)$

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Some questions regarding SDD equivalence still open

- Is SDD equivalence polynomially verifiable?

Restricted Restructuring

Definition (SDD equivalence)

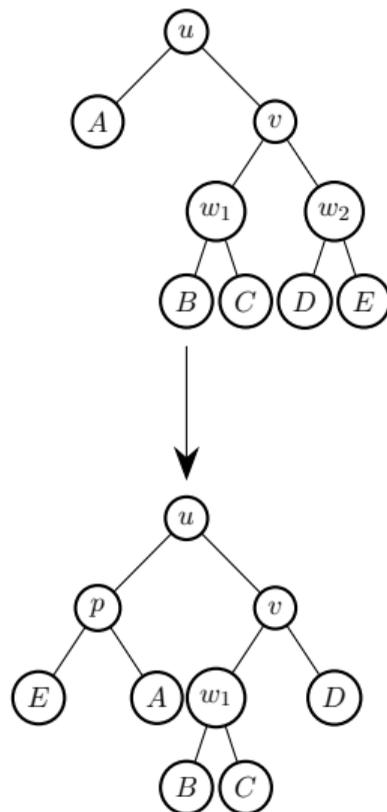
Input: Two SDDs D_1, D_2 respecting vtrees T_1, T_2

Question: Are D_1 and D_2 equivalent?

- If $T_1 = T_2$, SDD poly-time decidable
- If T_1 and T_2 arbitrary, Unknown
- If T_1 and T_2 very similar, again poly-time
 - ▶ Allow only local changes to the vtree

Restricted restructuring (r^*):

- Each step at most quadratic growth
- polynomially verifiable
- can simulate OBDD reordering



Local CNFs

Lifting method can be expanded to larger classes of CNFs called *local CNFs*

Definition (Local CNF)

Let φ be a reduced CNF with n variables. partition (ψ_1, ψ_2) of φ is called *monotone*, if each $x \in \text{var}(\psi_1) \cap \text{var}(\psi_2)$ appears only positively or only negatively

Let $C \in \varphi$. C has *monotone protrusion*, if there is a $\psi \subset \varphi$ such that

- $\text{var}(C) \cap \text{var}(\varphi \setminus \psi) = \emptyset$
- $(\psi, \varphi \setminus \psi)$ is a monotone protrusion
- $|\text{var}(\{C \mid \text{var}(C) \cap \text{var}(\psi) \neq \emptyset\})| \in \mathcal{O}(\log n)$

A CNF φ is called *local*, if every $C \in \varphi$ has a monotone protrusion.

Every reduced monotone $(k, \sqrt{\log n})$ -CNF is local, but the class of local CNFs is larger. For example, if the Gaifman graph of φ consists of many small components, then φ is local
lifting method also works on all local CNFs with the same proof idea