

# A smoothing procedure for Hermite subdivision schemes

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Joint work with Nira Dyn

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# Overview

- Point subdivision schemes and smoothing

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- Examples

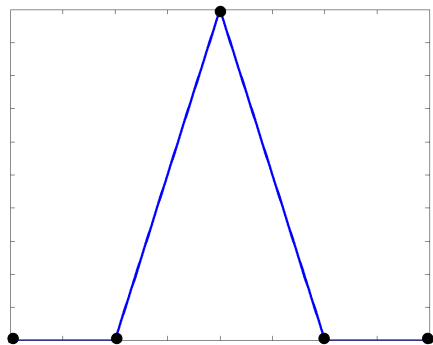
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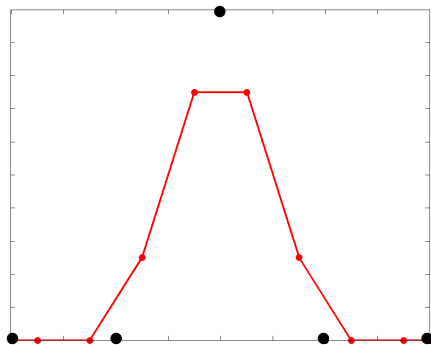
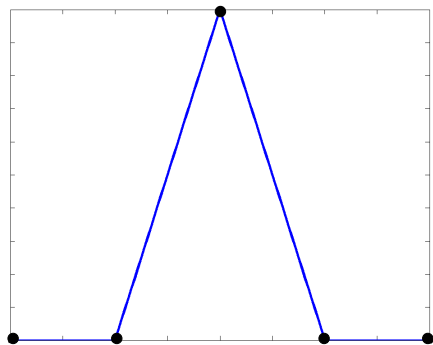
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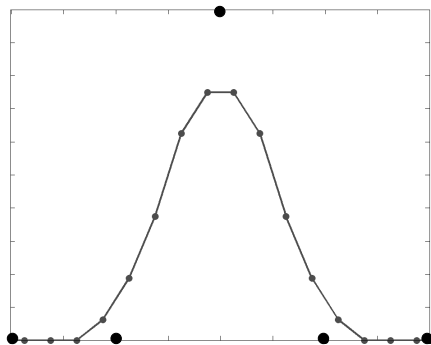
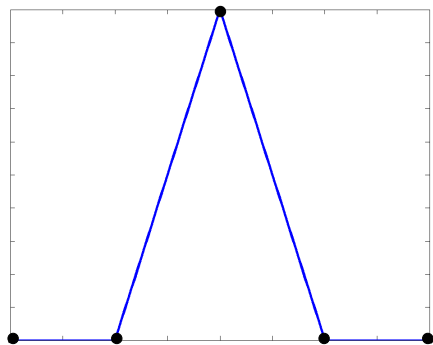




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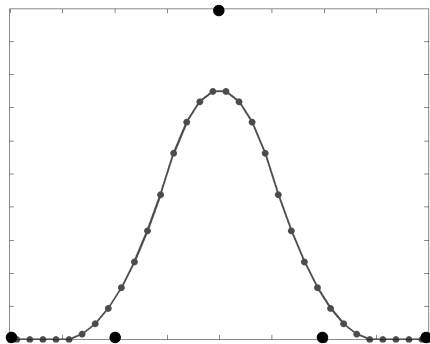
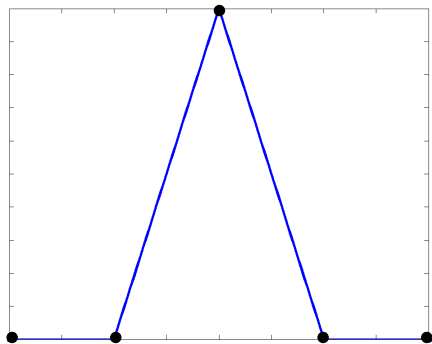
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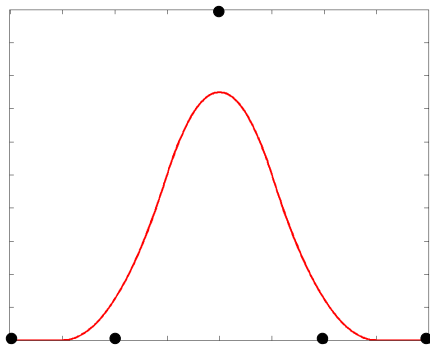
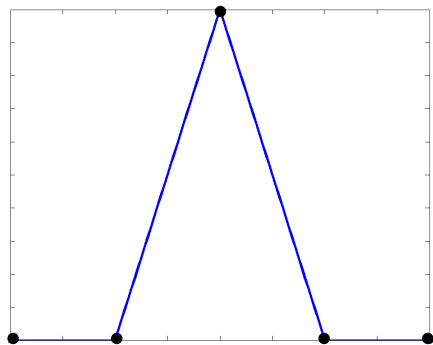
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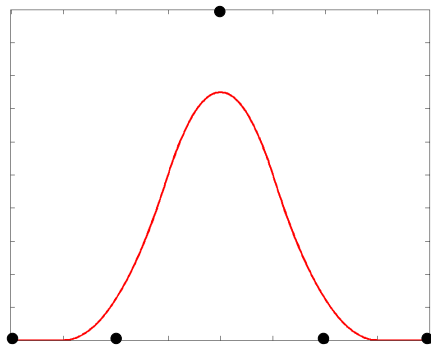
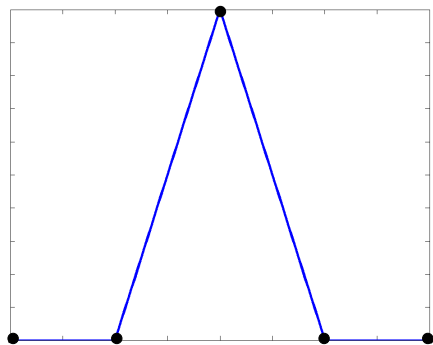
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The limit of this subdivision process is a degree 2 spline.



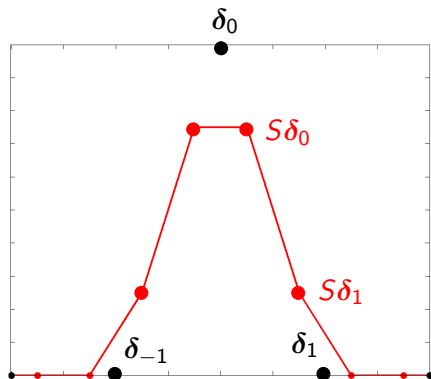
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Chaikin's algorithm in more detail:

$$(S\delta)_{2i} = \frac{3}{4}\delta_i + \frac{1}{4}\delta_{i+1}$$

$$(S\delta)_{2i+1} = \frac{1}{4}\delta_i + \frac{3}{4}\delta_{i+1}$$

- $S$  is a subdivision operator



Input:  $\delta$

First step:  $S\delta$

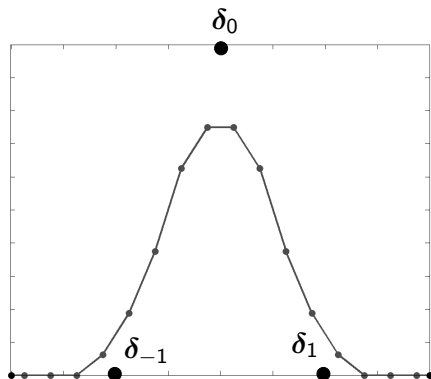
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Input:  $\delta$

Second step:  $S^2\delta$

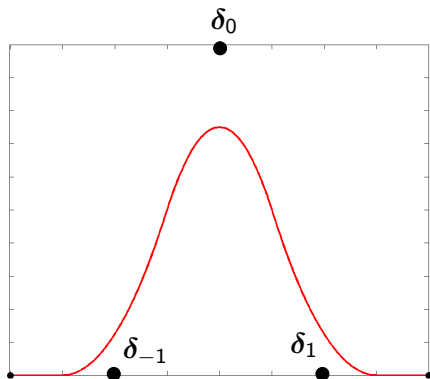
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Input:  $\delta$

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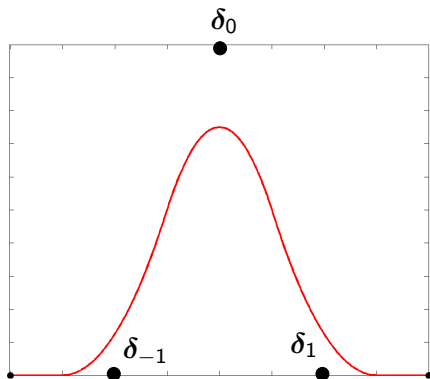
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- In this example the limit is  $C^1$



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## Point subdivision schemes

Start from input data  $p$ , a subdivision operator can be defined by two rules:

$$(Sp)_{2i} = \sum_{j \in \mathbb{Z}} a_{-2j} p_{i+j},$$

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For example, Chaikin's algorithm:

$$a(z) = \frac{1}{4}z^{-2} + \frac{3}{4}z^{-1} + \frac{3}{4} + \frac{1}{4}z.$$

# Smoothing of point subdivision schemes

Necessary condition for convergence:

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Smoothing of point subdivision schemes:

$$S_*, C^\ell \xrightarrow{\times \frac{z+1}{2z}} S, C^{\ell+1}$$

## Smoothing of point subdivision schemes

The mask of the Lane-Riesenfeld algorithm for degree  $k$  B-Splines:

$$a_k(z) = \frac{(z+1)^{k+1}}{(2z)^k}$$

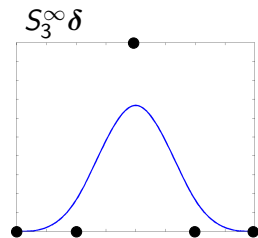
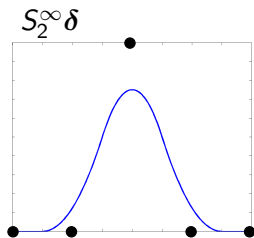
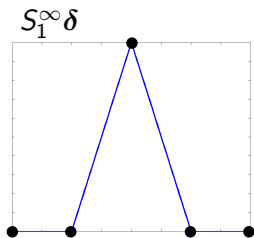
Apply subdivision operator  $S_k$  to 2D input data  $\delta = (i, \delta_{i,0})_{i \in \mathbb{Z}}$ :

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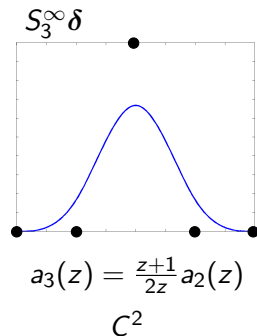
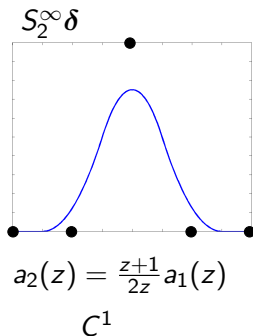
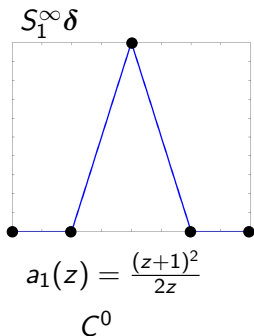


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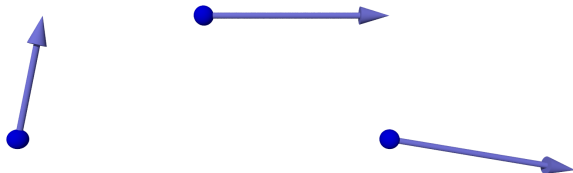


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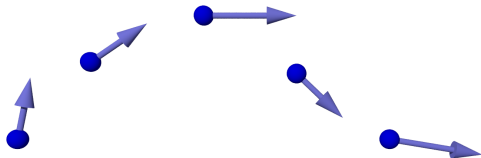
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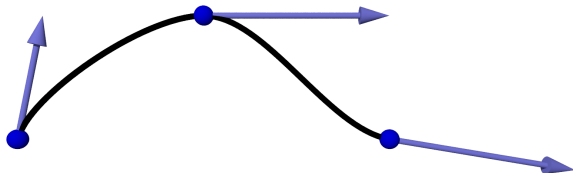
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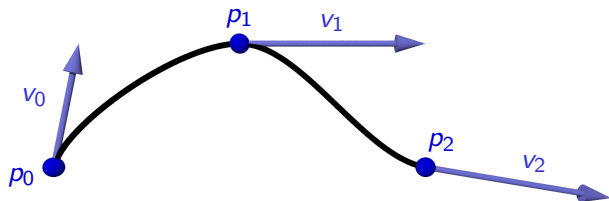
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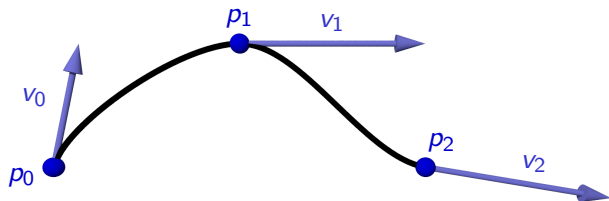
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Subdivision operator:  $S\left(\begin{smallmatrix} p \\ v \end{smallmatrix}\right)_i = \sum_{j \in \mathbb{Z}} \begin{pmatrix} a_{i-2j} & b_{i-2j} \\ c_{i-2j} & d_{i-2j} \end{pmatrix} \begin{pmatrix} p_j \\ v_j \end{pmatrix}$ .

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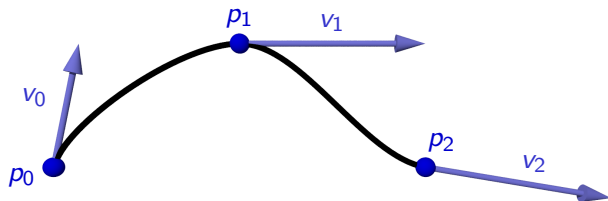


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- The iterates  $S^n\left(\begin{smallmatrix} p \\ v \end{smallmatrix}\right)$  describe the refined point-vector data
- $S^n\left(\begin{smallmatrix} p \\ v \end{smallmatrix}\right)$  converges to function and its derivative (after appropriate scaling)



## Smoothing of Hermite subdivision schemes

The spectral condition implies the existence of the Taylor scheme  $S_*$  with respect to the Taylor operator:

$$\begin{pmatrix} \Delta & -1 \\ 0 & 1 \end{pmatrix} S = \frac{1}{2} S_* \begin{pmatrix} \Delta & -1 \\ 0 & 1 \end{pmatrix}$$

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Disadvantage: Makes support larger by a maximum of 5.

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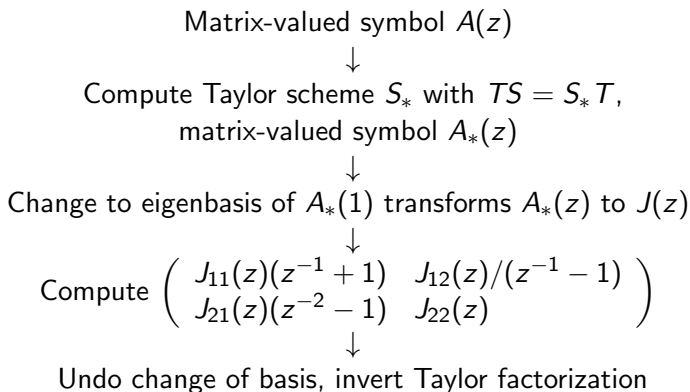


Compute  $\begin{pmatrix} J_{11}(z)(z^{-1} + 1) & J_{12}(z)/(z^{-1} - 1) \\ J_{21}(z)(z^{-2} - 1) & J_{22}(z) \end{pmatrix}$

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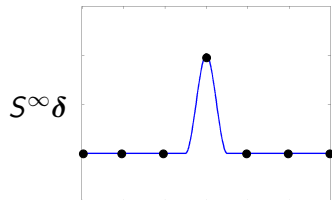
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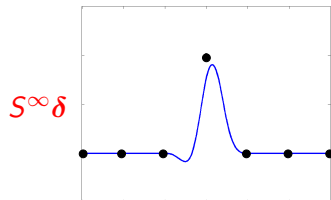
# Examples

We smoothen an interpolatory  $C^1$  Hermite scheme by J.-L. Merrien.

$C^1$  Hermite limit



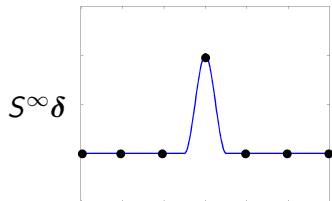
$C^2$  Hermite limit



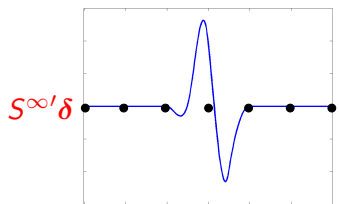
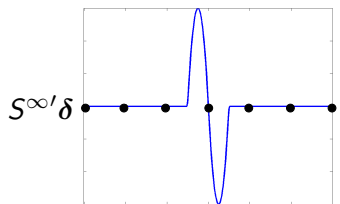
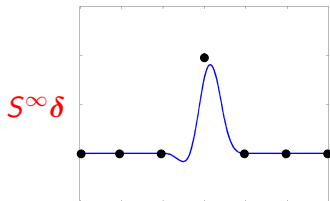
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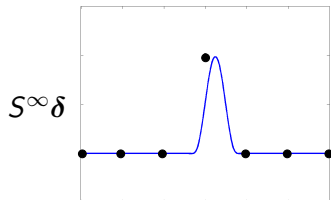
$C^2$  Hermite limit



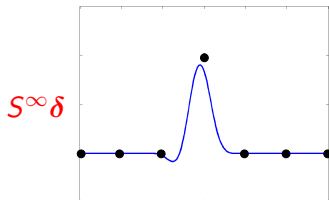
## Examples

We smoothen a  $C^2$  Hermite scheme constructed by a de Rham transform.

$C^2$  Hermite limit



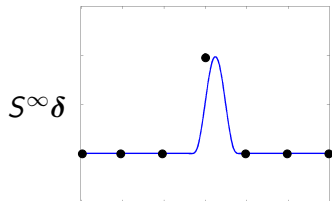
$C^3$  Hermite limit



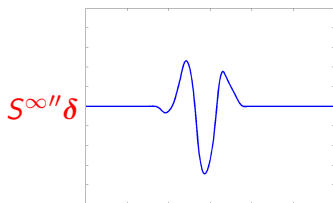
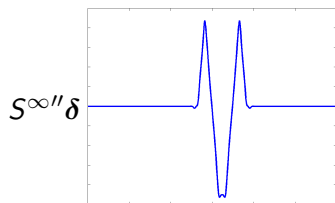
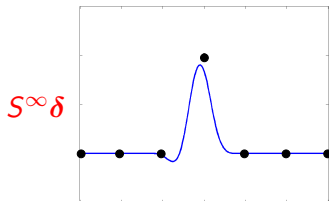
# Examples

We smoothen a  $C^2$  Hermite scheme constructed by a de Rham transform.

$C^2$  Hermite limit



$C^3$  Hermite limit



# Conclusion

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**Thank you!**



DOCTORAL PROGRAM  
DISCRETE MATHEMATICS



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## Smoothing of Hermite schemes

For example, if  $S$  has the mask  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$  and  $b(1) = 0$ , then the mask of the new Hermite scheme  $\mathcal{S}$  is given by

$$a(z) = \frac{(z+1)}{2z} \left( (z^{-2} - 2)b(z) + a(z) \right),$$

$$b(z) = \frac{1}{2} \frac{zb(z)}{(1-z)},$$

$$c(z) = \frac{1}{2}(z^{-2} - 1) \left( c(z) - a(z)(z^{-1} - 2) \right. \\ \left. + d(z)(z^{-2} - 2) - b(z)(z^{-1} - 2)(z^{-2} - 2) \right),$$

$$d(z) = \frac{1}{2}(d(z) - (z^{-1} - 2)b(z)).$$