The classification of anisotropic Besov spaces

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Lehrstuhl A für Mathematik, RNTH

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Anisotropic Besov spaces

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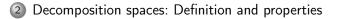


Anisotropic Besov spaces

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Anisotropic Besov spaces





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Anisotropic Besov spaces

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Anisotropic Besov spaces

- 2 Decomposition spaces: Definition and properties
- 3 Rigidity theorem for decomposition spaces



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Anisotropic Besov spaces

- 2 Decomposition spaces: Definition and properties
- 3 Rigidity theorem for decomposition spaces
- 4 Classifying anisotropic coverings

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Overview

1 Anisotropic Besov spaces

2 Decomposition spaces: Definition and properties

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4 Classifying anisotropic coverings

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Anisotropic Besov spaces

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A matrix $A \in GL(d, \mathbb{R})$ is called expansive if all eigenvalues of A have modulus > 1.

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Let A be expansive. A function $\psi \in \mathcal{S}(\mathbb{R}^d)$ is called an A-wavelet if $\widehat{\psi}$ is compactly supported away from zero, and fulfills

$$orall \xi \in \mathbb{R}^d \setminus \{0\} \hspace{0.1 in} : \hspace{0.1 in} \sum_{j \in \mathbb{Z}} |\widehat{\psi}((\mathcal{A}^{\mathcal{T}})^{-j}\xi)|^2 = 1 \hspace{0.1 in} .$$

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A Schwartz function φ is called A-scaling function if

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Note: A-wavelets and scaling functions always exist.

Definition (M. Bownik, 2005)

 $A \in \operatorname{GL}(d,\mathbb{R})$ expansive matrix, ψ, ϕ an A-wavelet and scaling function, respectively.

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Given $f \in S'(\mathbb{R}^d)$, let

$$\|f\|_{\dot{B}^{\alpha}_{p,q}(A)} = \left\| \left(|\det(A)|^{j\alpha} \|f * \psi_j\|_p \right)_{j \in \mathbb{Z}} \right\|_{\ell^q} \tag{1}$$

denote the homogeneous Besov quasi-norm. The homogeneous Besov space $\dot{B}^{\alpha}_{p,q}(A)$ associated to A consists of all f with $||f||_{\dot{B}^{\alpha}_{p,q}(A)} < \infty$.

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denote the homogeneous Besov quasi-norm. The homogeneous Besov space $\dot{B}^{\alpha}_{p,q}(A)$ associated to A consists of all f with $||f||_{\dot{B}^{\alpha}_{p,q}(A)} < \infty$. We identify elements of $\dot{B}^{\alpha}_{p,q}(A)$ that only differ by a polynomial.

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Anisotropic Besov spaces

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(b) Define $\psi_0^i = \varphi$, as well as $\psi_j^i(x) = |\det(A)|^j \psi(A^j x)$ for $j \in \mathbb{N}$.



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$$\|f\|_{B^{\alpha}_{p,q}(A)} = \left\| \left(|\det(A)|^{j\alpha} \left\| f * \psi^{j}_{j} \right\|_{p} \right)_{j \in \mathbb{N}} \right\|_{\ell^{q}}$$
(2)

The inhomogeneous anisotropic Besov space $B_{p,q}^{\alpha}(A)$ associated to A consists of all tempered distributions f with $\|f\|_{B_{p,q}^{\alpha}(A)} < \infty$.

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Known properties of anisotropic Besov spaces

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Main questions for this talk

Given two expansive matrices A, B, we call them homogeneously equivalent $(A \sim_h B)$ whenever $\dot{B}^{\alpha}_{p,q}(A) = \dot{B}^{\alpha}_{p,q}(B)$ holds for all $0 < p, q \leq \infty, \alpha \in \mathbb{R}$.

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- Can one decide whether $A \sim_h B$ or $A \sim_i B$ holds?
- Do \sim_h and \sim_i differ?

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Anisotropic Besov spaces

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Decomposition spaces (Feichtinger/Gröbner)

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Informal description: Cover the frequencies by a family of open relatively compact sets. Decompose functions using a subordinate partition of unity. Introduce a norm by locally taking L^p -norms, and then globally combine using weighted ℓ^q norm.

Definition

Let $\mathcal{O} \subset \mathbb{R}^d$ be open, and $\mathcal{Q} = (Q_i)_{i \in I}$ a family of open, subsets $Q_i \subset \mathcal{O}$ with compact closure in \mathcal{O} .

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 - (ii) Admissibility: $\sup_{i \in I} \sup_{j \in I, Q_i \cap Q_j \neq \emptyset} \frac{\lambda(Q_i)}{\lambda(Q_j)} < \infty$.
- (b) Q is called an almost structured admissible covering (a.s.a.c.) if it is an admissible covering, and there exist (Q'_i)_{i∈1}, nonempty open bounded sets and T_i ∈ GL(d, ℝ) and b_i ∈ ℝ^d with:

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(i) For all
$$i \in I$$
: $\overline{T_i Q'_i + b_i} \subset Q_i$.

- (ii) The quantity $\sup_{i,j:Q_i \cap Q_i \neq \emptyset} ||T_i^{-1}T_j||$ is finite. (iii) The set $\{Q'_i : i \in I\}$ is finite.
- (iv) The family $(T_iQ'_i + b_i)_{i \in I}$ is an admissible covering.

The tuple $((T_i)_{i \in I}, (b_i)_{i \in I}, (Q'_i)_{i \in I})$ are called standardization of Q.

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Partitions of unity

Definition

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Let $Q = (Q_i)_{i \in I}$ denote an almost structured admissible covering with standardization $((T_i)_{i \in I}, (b_i)_{i \in I}, (Q'_i)_{i \in I})$. Let $0 . We call a family <math>(\varphi_i)_{i \in I}$ of functions an L^{*p*}-BAPU with respect to Q if it has the following properties:

(i) For all
$$i \in I : \varphi_i \in C_c^{\infty}(\mathcal{O})$$
.
(ii) For all $i \in I : \varphi_i \equiv 0$ on $\mathbb{R}^d \setminus Q_i$.
(iii) $\sum_{i \in I} \varphi \equiv 1$ on \mathcal{O} .
(iv) $\sup_{i \in I} |\det(T_i)|^{\frac{1}{t}-1} ||\mathcal{F}^{-1}\varphi_i||_{L^p} < \infty$. Here $t = \min(p, 1)$.

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Lemma (Feichtinger, Voigtlaender) BAPU's exist.

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Weights associated to coverings

Definition

Let $Q = (Q_i)_{i \in I}$ denote an admissible covering, and let $v : I \to \mathbb{R}^+$ denote a weight. The weight is called *Q*-moderate if

$$\sup_{i,j\in I:Q_i\cap Q_j\neq\emptyset}\frac{v(i)}{v(j)}<\infty \ .$$

Given $0 < q \le \infty$, let $\ell_v^q(I) = \{c = (c_i)_{i \in I} \in \mathbb{C}^I : (c_i v(i))_{i \in I} \in \ell^q(I)\}$, with the obvious (quasi-)norm.

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Definition (Feichtinger/Gröbner, Voigtlaender) Given a.s.a.c. $Q = (Q_i)_{i \in I}$, a Q-moderate weight v, $0 \le p, q \le \infty$.



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Given a.s.a.c. $Q = (Q_i)_{i \in I}$, a Q-moderate weight v, $0 \le p, q \le \infty$. Let $(\varphi_i)_{i \in I}$ denote an L^{*p*}-BAPU associated to Q. Given $u \in \mathcal{D}'(\mathcal{O})$, we define its decomposition space (quasi-)norm as

$$\|u\|_{\mathcal{D}(\mathcal{Q},\mathrm{L}^{p},\ell_{\nu}^{q})} = \left\| \left(\|\mathcal{F}^{-1}(\varphi_{i}\cdot u)\|_{\mathrm{L}^{p}} \right)_{i\in I} \right\|_{\ell_{\nu}^{q}} .$$
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The decomposition space $\mathcal{D}(\mathcal{Q}, L^p, \ell^q_v)$ is the space of all $u \in \mathcal{D}'(\mathcal{O})$ for which this (quasi-)norm is finite.

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Anisotropic Besov spaces

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Theorem (Feichtinger/Gröbner)

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- Large variety of admissible coverings allows diverse ways of measuring the decay. Describes homogeneous and inhomogeneous isotropic Besov spaces, α -modulation spaces, shearlet and curvelet approximation spaces,

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- Central message: Frequency covering is the decisive feature!
- Large variety of admissible coverings allows diverse ways of measuring the decay. Describes homogeneous and inhomogeneous isotropic Besov spaces, α-modulation spaces, shearlet and curvelet approximation spaces, shearlet coorbit spaces (see upcoming talk by René Koch), and anisotropic Besov spaces.
- Decomposition spaces provide a unified framework for many embedding results, either between different decomposition spaces, or of decomposition spaces into well-known smoothness spaces such as Sobolev spaces (F. Voigtlaender).

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Induced covering

Definition

Let A denote an expansive matrix. Let $Q \Subset \mathbb{R}^d \setminus \{0\}$ be open, and such that

$$\bigcup_{j\in\mathbb{Z}}A^{j}Q=\mathbb{R}^{d}\setminus\{0\}\,\,.$$

Then $Q_A = (A^j Q)_{j \in \mathbb{Z}}$ is called the homogeneous covering induced by A.



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Then $Q_A = (A^j Q)_{j \in \mathbb{Z}}$ is called the homogeneous covering induced by A. Letting $Q_j^i = A^j Q$, for $j \ge 1$, and choosing Q_0^j open, relatively compact such that

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defines Q_A^i , the inhomogeneous covering induced by A.

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Intuition

$$Q_j = \widehat{\psi_j}^{-1}(\mathbb{C} \setminus \{0\}) \ , \ \ Q_j^i = \widehat{\psi_j}^{i-1}_j(\mathbb{C} \setminus \{0\})$$

and the wavelet systems are BAPUs.

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Theorem

Let A denote an expansive matrix, and Q_A a homogeneous covering induced by A^T .

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Let A denote an expansive matrix, and Q_A a homogeneous covering induced by A^T . For $\alpha \in \mathbb{Z}$, define

$$\mathbf{v}_{lpha,\mathcal{A}}:\mathbb{Z} o\mathbb{R}^+ \ , \mathbf{v}_{lpha,\mathcal{A}}(j)=|\mathrm{det}(\mathcal{A})|^{jlpha}$$

Theorem

Let A denote an expansive matrix, and Q_A a homogeneous covering induced by A^T . For $\alpha \in \mathbb{Z}$, define

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Denote by $\rho : \mathcal{S}'(\mathbb{R}^d) \to \mathcal{D}'(\mathbb{R}^d)$ the restriction map.

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Denote by $\rho : S'(\mathbb{R}^d) \to \mathcal{D}'(\mathbb{R}^d)$ the restriction map. Then $\rho \circ \mathcal{F}$ is a topological isomorphism

$$\rho \circ \mathcal{F} : \dot{B}^{\alpha}_{\rho,q}(\mathcal{A}) \to \mathcal{D}(\mathcal{Q}_{\mathcal{A}}, \mathrm{L}^{p}, \ell^{q}_{v_{\alpha,\mathcal{A}}}) \;.$$

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Similarly, if Q_A^i denote an inhomogeneous covering induced by A^T , then

$$\rho \circ \mathcal{F} : B^{\alpha}_{p,q}(\mathcal{A}) \to \mathcal{D}(\mathcal{Q}^{i}_{\mathcal{A}}, \mathrm{L}^{p}, \ell^{q}_{v_{\alpha,\mathcal{A}}}) \;.$$

is a topological isomorphism, as well. Here $v_{\alpha,A}$ denotes the restriction of the weight for the homogeneous setting to \mathbb{N}_0 .

Overview

Anisotropic Besov spaces

2 Decomposition spaces: Definition and properties

3 Rigidity theorem for decomposition spaces

4 Classifying anisotropic coverings

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Anisotropic Besov spaces

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Anisotropic Besov spaces

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Definition

Admissible coverings $Q = (Q_i)_{i \in I}$ and $\mathcal{P} = (P_j)_{j \in J}$ are weakly equivalent



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Weights v on I and w on J are equivalent if

$$\sup_{i,j,Q_i\cap P_j\neq\emptyset}\frac{v(i)}{w(j)}+\frac{w(j)}{v(i)}<\infty \ .$$

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Anisotropic Besov spaces

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Theorem (Feichtinger/Gröbner, 1985; F. Voigtlaender, 2016) Let $\mathcal{P} = (P_i)_{i \in I}$, $\mathcal{Q} = (Q_j)_{j \in J}$ denote a.s.a.c.'s, consisting of pathwise connected sets.

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Anisotropic Besov spaces

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- (c) For all $(p,q)\in [1,\infty]^2$ and all pairs v_1,v_2 of equivalent weights,

$$\mathcal{D}(\mathcal{P}, L^p, \ell^q_{v_1}) = \mathcal{D}(\mathcal{Q}, L^p, \ell^q_{v_2})$$
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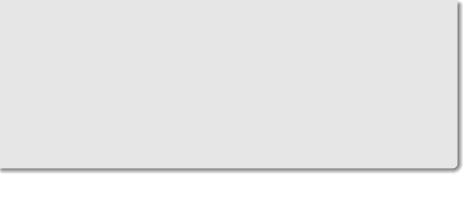
$$\mathcal{D}(\mathcal{P}, L^p, \ell^q_{v_1}) = \mathcal{D}(\mathcal{Q}, L^p, \ell^q_{v_2})$$
.

Note: If v denotes the constant weight, then $\mathcal{D}(\mathcal{P}, L^2, \ell_v^2) = L^2(\mathbb{R}^d)$, for every a.s.a.c. covering \mathcal{P} .

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Anisotropic Besov spaces

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The scales (B^α_{p,q}(A))_{p,q,α} and (B^α_{p,q}(B))_{p,q,α} coincide iff they coincide for one nontrivial pair of exponents.

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 - A ~_B B iff the induced inhomogeneous coverings $Q_{A^{T}}^{i}$ and $Q_{B^{T}}^{i}$ are weakly equivalent.
- A ~_h B is equivalent to the property that A, B induce the same scale of anisotropic Hardy spaces (~→ M. Bownik).

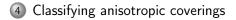
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Overview

Anisotropic Besov spaces

2 Decomposition spaces: Definition and properties

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- $A^T \sim_i B^T$ has similar formulation.
- Fairly obvious: $A^T \sim_h (A^T)^k$, for $k \in \mathbb{N}$.
- Simple exercise: Checking $A \sim_h B$ or $A \sim_i B$ for A, B diagonal.

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Anisotropic Besov spaces

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Lemma (M. Bownik; HF & J. Cheshmavar)

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Corollary

 $A \sim_h B$ implies $A \sim_i B$.

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Corollary

 $A \sim_h B$ implies $A \sim_i B$. The converse holds if A, B are diagonal.

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Anisotropic Besov spaces

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Definition

Given a matrix $A \in \mathbb{C}^{d \times d}$, we define for r > 0 and $m \in \mathbb{N}_0$

$$E(A,r,m) = \operatorname{span} \left(\bigcup_{|\lambda|=r} \operatorname{Ker}(A - \lambda I_d)^m \cup \bigcup_{|\lambda| < r} \operatorname{Ker}(A - \lambda I_d)^d \right) \ .$$

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Strategy for deciding $A \sim_h B$

Given A, B, compute expansive normal forms A', B', and compare.

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Strategy for deciding $A \sim_h B$

Given A, B, compute expansive normal forms A', B', and compare. Once the spectra of A, B are known, this can be carried out using standard linear algebra methods.

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Anisotropic Besov spaces

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• W.l.o.g. A has only one eigenvalue λ , and that is non-real.

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• W.l.o.g. A has only one eigenvalue λ , and that is non-real. • Given $z \in \mathbb{C}$, write

$$M_z = \left(egin{array}{cc} \operatorname{Re}(z) & \operatorname{Im}(z) \ -\operatorname{Im}(z) & \operatorname{Re}(z) \end{array}
ight) \; .$$

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W.I.o.g. A has only one eigenvalue λ, and that is non-real.
Given z ∈ C, write

$$M_z = \left(egin{array}{cc} \operatorname{Re}(z) & \operatorname{Im}(z) \\ -\operatorname{Im}(z) & \operatorname{Re}(z) \end{array}
ight) \; .$$

With a suitable matrix C, we get

$$CAC^{-1} = \begin{pmatrix} M_{\lambda} & M_{z_1} & & & \\ & M_{\lambda} & M_{z_2} & & & \\ & & \ddots & \ddots & & \\ & & & M_{\lambda} & M_{z_{d/2-1}} \\ & & & & M_{\lambda} \end{pmatrix} ,$$

with $z_1, z_2 \ldots \in \{0, 1\} \subset \mathbb{C}$.

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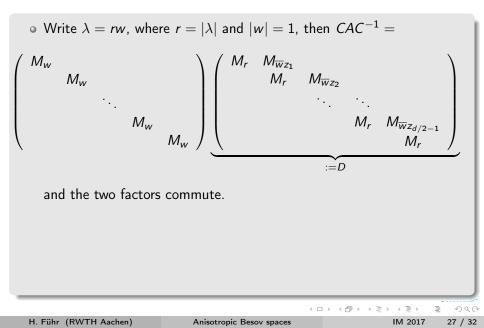
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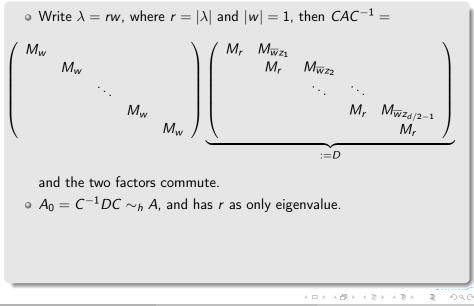
Anisotropic Besov spaces

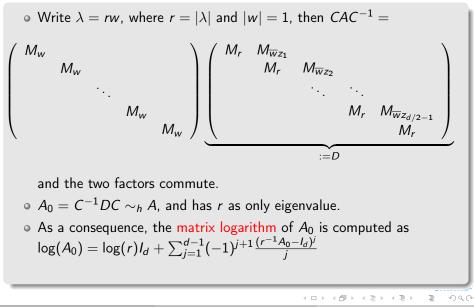
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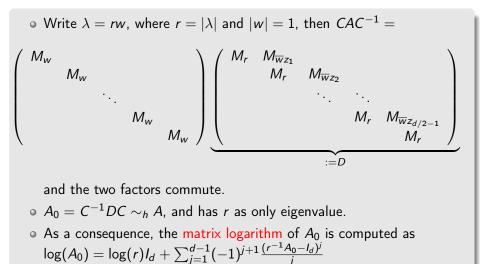




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• Define $A' = \exp(s \log(A_0))$, where $s = \ln(2)/d \ln(r)$.

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- If the polynomial map $k \mapsto P_k Q_k$ is bounded, it is constant.
- $A^{-1}B^1 = A^{-2}B^2$ implies A = B.

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The inhomogeneous case

Theorem (HF & J. Cheshmavar)

Let A, B be in expansive normal form.

The inhomogeneous case

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Let A, B be in expansive normal form. Let $\lambda_1 > \lambda_2 > ... > \lambda_k$ denote the distinct eigenvalues of A, and assume that A has the block diagonal form

$$A = \begin{pmatrix} J_1 & & & \\ & J_2 & & \\ & & \ddots & \\ & & & & J_k \end{pmatrix}$$

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such that $\forall 1 \leq i \leq k$: $(J_i - \lambda_i I_{d_i})^d = 0$.

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Let A, B be in expansive normal form. Let $\lambda_1 > \lambda_2 > \ldots > \lambda_k$ denote the distinct eigenvalues of A, and assume that A has the block diagonal form

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such that $\forall 1 \leq i \leq k : (J_i - \lambda_i I_{d_i})^d = 0$. Then $A^T \sim_i B^T$ if and only if

$$B = \left(egin{array}{cccc} J_1 & * & * & * \\ & J_2 & * & * \\ & & \ddots & * \\ & & & & J_k \end{array}
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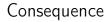
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$$A = \left(\begin{array}{cc} 3 & 0 \\ 0 & 2 \end{array}\right) \ , \ B = \left(\begin{array}{cc} 3 & 0 \\ 1 & 2 \end{array}\right)$$

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Image: Image:

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fulfill $A \sim_i B$, but $A \not\sim_h B$.

• If A, B are expansive diagonal matrices with positive entries, then $A \sim_h B$ iff $A = B^{\epsilon}$, for some $\epsilon > 0$.



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 Main results of the talk: Decomposition space description of anisotropic Besov spaces, and resulting classification of dilation matrices.

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- Further consequences of the decomposition space description: Sharp embedding theorems into Sobolev spaces, or other Besov spaces (anisotropic and isotropic). (Not yet fully explored.)
- The present talk presents a case study of the power of decomposition space methods for the analysis of function spaces defined in terms of families of convolution products.

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