

Non-Consistent Cell-Average Multiresolution Operators: The Case of the PPH Nonlinear Prediction Operator

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Main focus

Construction of a MR prediction in cell-average context which avoids the Gibbs phenomenon in the discontinuities

Review Multiresolution “à la Harten”

- Decimation and prediction operators
- Cell-average and prediction based on polynomial interpolation

Non consistency. Strategy (AY)

- Motivation. Classical strategy (E1)
- Properties of the non-consistent operators

PPH non-linear prediction

- Motivation and definition
- Properties: order, stability and monotonicity
- Numerical examples

Operators

- Let V^k be a discrete space, where k is the level of resolution ($\uparrow k \equiv \uparrow$ resolution).
- Define transfer operators connecting consecutive levels,
 - **Decimation**, $\mathcal{D}_k^{k-1} : V^k \rightarrow V^{k-1}$, operator **linear** and **onto**
 - **Prediction**, $\mathcal{P}_{k-1}^k : V^{k-1} \rightarrow V^k$, **no necessary linear**
 - $e^k = f^k - \mathcal{P}_{k-1}^k \mathcal{D}_k^{k-1} f^k$

Theorem

$$\mathcal{D}_k^{k-1} \mathcal{P}_{k-1}^k = I_{V^{k-1}} \iff \mathbf{e}^k \in \mathcal{N}(\mathcal{D}_k^{k-1})$$

$$\dim \mathcal{N}(\mathcal{D}_k^{k-1}) = \dim V^k - \dim V^{k-1}$$

If $\{\mu_j^k\}$ is a basis of $\mathcal{N}(\mathcal{D}_k^{k-1})$, therefore

$$\mathbf{e}^k = \sum d_j^k \mu_j^k$$

Define the operators

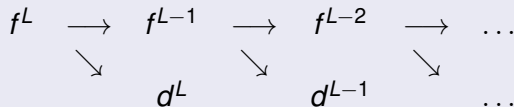
$$\begin{array}{lll} G_k : \mathcal{N}(\mathcal{D}_k^{k-1}) & \longrightarrow & \mathcal{G}^k \\ \mathbf{e}^k & \longrightarrow & \{d_j^k\} \end{array} \quad \begin{array}{lll} E_k : \mathcal{G}^k & \longrightarrow & \mathcal{N}(\mathcal{D}_k^{k-1}) \\ d^k & \longrightarrow & \sum d_j^k \mu_j^k \end{array}$$

Therefore,

$$f^k \xleftrightarrow{1:1} \{f^{k-1}, d^k\}$$

Multi-scale decomposition

Repeat several times,



$$f^L \xleftrightarrow{1:1} Mf^L = \{f^0, d^1, \dots, d^L\}$$

Definition (Order of the scheme)

Let p be a polynomial of degree r , i.e., $p(x) \in \Pi^r(\mathbb{R})$; and let p^k be the discretization on the level k . The multiresolution scheme $\{\mathcal{D}_k^{k-1}, \mathcal{P}_{k-1}^k\}$ has order $r + 1$ if and only if

$$\mathcal{P}_{k-1}^k \mathcal{D}_k^{k-1} p^k = p^k, \text{ for each resolution level } k.$$

Definition (Stability of MR)

The reconstruction algorithm is stable with respect to the norm $\|\cdot\|$ if: $\exists C$ such that $\forall j_0 > 0$,

$$\forall (f^0, d^1, \dots, d^{j_0}) \mapsto f^{j_0},$$

$$(\hat{f}^0, \hat{d}^0, \dots, \hat{d}^{j_0}) \mapsto \hat{f}^{j_0} :$$

$$\|f^{j_0} - \hat{f}^{j_0}\| \leq C \sup(\|f^{j_0-1} - \hat{f}^{j_0-1}\|, \|d^{j_0} - \hat{d}^{j_0}\|). \quad (1)$$

Cell-average analysis in 1D

- $X^k = \{x_j^k\}$, $x_j^k = jh_k$
 $j = 0, \dots, J_k$ $J_k h_k = 1$, $h_k = 2^{-k} J_0$,
- $c_j^k = [x_{j-1}^k, x_j^k]$, $j = 1, \dots, J_k$

Definition

We define the discretization operator as,

$$f_j^k = \int_{c_j^k} f(x) dx, \quad j = 1, \dots, J_k$$

We define the decimation operator as,

$$(\mathcal{D}_k^{k-1} f^k)_j = \frac{1}{2}(f_{2j-1}^k + f_{2j}^k) = f_j^{k-1}, \quad j = 1, \dots, J_{k-1}$$

Prediction operator in 1D: MR based on polynomial interpolation

- We take $\Pi^r(\mathbb{R}) = \{p(x) = \sum_{0 \leq l \leq r} a_l x^l : a_l \in \mathbb{R}\}$
- For each point x_j^{k-1} we have the polynomial,

$$p_j^r(x) = \sum_{l=0}^r a_l x^l$$

- The coefficients a_l will be determined with the $r + 1$ conditions:

$$f_{j-\frac{r}{2}+l}^{k-1} = \int_{c_{j-\frac{r}{2}+l}^{k-1}} p_j^r(x) dx \quad l = 0, \dots, r$$

Prediction operator in 1D: MR based on polynomial interpolation

- $r = 0$

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = f_j^{k-1} \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = f_j^{k-1} \end{cases}$$

- $r = 1$ Chaikin's scheme [Non-consistent operator]

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = \frac{3}{4} f_j^{k-1} + \frac{1}{4} f_{j-1}^{k-1} \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = \frac{3}{4} f_j^{k-1} + \frac{1}{4} f_{j+1}^{k-1} \end{cases}$$

- $r = 2$, CA scheme.

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = f_j^{k-1} + \frac{1}{8}(f_{j-1}^{k-1} - f_{j+1}^{k-1}) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = f_j^{k-1} - \frac{1}{8}(f_{j-1}^{k-1} - f_{j+1}^{k-1}) \end{cases}$$

References

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- F. ARÀNDIGA, R. DONAT (2000): “Nonlinear multiscale descompositions: The approach of A. Harten”, *Numerical Algorithms*, 23, 175-216
- A. COHEN (2003): “Numerical Analysis of Wavelet Methods”, *Elsevier*
- A. HARTEN (1993): “Discrete multiresolution analysis and generalized wavelets”, *J. Appl. Numer. Math.*, 12, 153–192
- A. HARTEN (1996): “Multiresolution Representation of data: General framework, *SIAM J. Numer. Anal.*”, 33, 1205–1256

Making the details

We define the errors between f^k and the prediction as:

$$e_{2j-1}^k = f_{2j-1}^k - (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1}, \quad 1 \leq j \leq J_{k-1}$$

$$e_{2j}^k = f_{2j}^k - (\mathcal{P}_{k-1}^k f^{k-1})_{2j}, \quad 1 \leq j \leq J_{k-1}$$

$$f^k \equiv (f^{k-1}, e^k)$$

Motivation

$$(d_1^k)_j = \frac{1}{2}(e_{2j-1}^k - e_{2j}^k)$$

$$(d_0^k)_j = \frac{1}{2}(e_{2j-1}^k + e_{2j}^k)$$

Motivation

$$(d_1^k)_j = \frac{1}{2}(e_{2j-1}^k - e_{2j}^k)$$
$$(d_0^k)_j = \frac{1}{2}(e_{2j-1}^k + e_{2j}^k)$$

The consistency property is:

$$\mathcal{D}_k^{k-1} \mathcal{P}_{k-1}^k = I_{V^{k-1}} \rightarrow \mathcal{D}_k^{k-1} e^k = 0$$

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Non-consistency property:

$$\mathcal{D}_k^{k-1} \mathcal{P}_{k-1}^k \neq I_{V^{k-1}} \rightarrow \mathcal{D}_k^{k-1} e^k \neq 0$$

Motivation

$$(d_1^k)_j = \frac{1}{2}(e_{2j-1}^k - e_{2j}^k)$$

$$(d_0^k)_j = f_j^{k-1} - (\mathcal{D}_k^{k-1} \mathcal{P}_{k-1}^k f^{k-1})_j = f_j^{k-1} - \xi_j^{k-1}$$

Non-consistency property:

$$\mathcal{D}_k^{k-1} \mathcal{P}_{k-1}^k \neq I_{V^{k-1}} \rightarrow \mathcal{D}_k^{k-1} e^k \neq 0 \rightarrow f^k \equiv (f^{k-1}, d_1^k)$$

Strategy (E1)

$$f_{2j}^k = (\mathcal{P}_{k-1}^k f^{k-1})_{2j} + (d_0^k)_j - (d_1^k)_j$$

Strategy (E1)

$$f_{2j}^k = (\mathcal{P}_{k-1}^k f^{k-1})_{2j} + f_j^{k-1} - \xi_j^{k-1} - (d_1^k)_j$$

Strategy (E1)

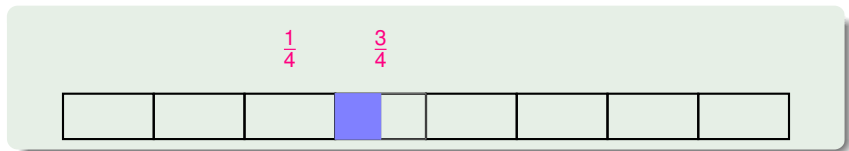
$$f_{2j}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j} + \color{red}{f_j^{k-1}} - \color{red}{\xi_j^{k-1}}}_{(\check{\mathcal{P}}_{k-1}^k f^{k-1})_{2j}} - \underbrace{(d_1^k)_j}_{\check{e}_{2j}^k}$$

Strategy (E1)

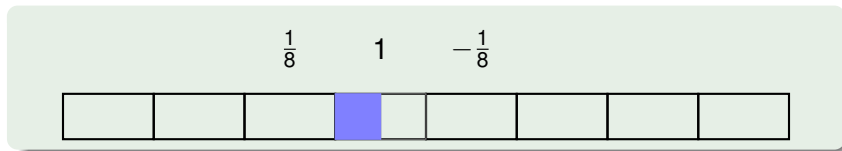
$$f_{2j-1}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j-1}}_{(\check{\mathcal{P}}_{k-1}^k f^{k-1})_{2j-1}} + \underbrace{(d_0^k)_j + (d_1^k)_j}_{\check{e}_{2j-1}^k}$$

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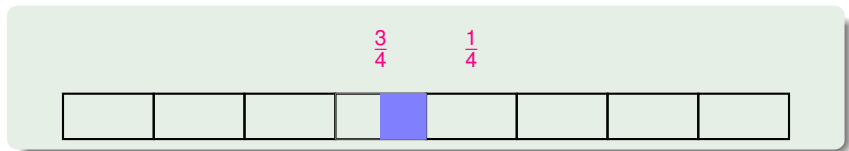
Strategy (E1). Example, \mathcal{P}_{k-1}^k



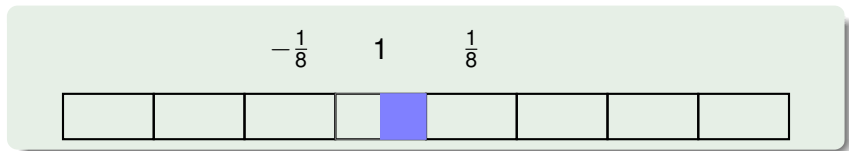
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Strategy (E1). Example, \mathcal{P}_{k-1}^k



Strategy (E1). Example, \check{P}_{k-1}^k



Strategy (AY)

$$f_{2j}^k = (\mathcal{P}_{k-1}^k f^{k-1})_{2j} + (d_0)_j^k - (d_1^k)_{i,j}$$

Strategy (AY)

$$f_{2j}^k = (\mathcal{P}_{k-1}^k f^{k-1})_{2j} + \cancel{f_j^{k-1}} - \cancel{\xi_j^{k-1}} - (d_1^k)_{i,j}$$

Strategy (AY)

$$f_{2j}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j}}_{(\mathcal{P}_{k-1}^k f^{k-1})_{2j}} + \underbrace{f_j^{k-1} - \xi_j^{k-1} - (d_1^k)_j}_{e_{2j}^k}$$

Strategy (AY)

$$f_{2j-1}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j-1}}_{(\mathcal{P}_{k-1}^k f^{k-1})_{2j-1}} + \underbrace{(d_0^k)_j + (d_1^k)_j}_{e_{2j-1}^k}$$

$$f_{2j}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j}}_{(\mathcal{P}_{k-1}^k f^{k-1})_{2j}} + \underbrace{(d_0^k)_j - (d_1^k)_j}_{e_{2j}^k}$$

Strategy (E1) vs Strategy (AY)

Cell $(2j)$:

(E1)

$$f_{2j}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j} + f_j^{k-1} - \xi_j^{k-1}}_{(\check{\mathcal{P}}_{k-1}^k f^{k-1})_{2j}} - \underbrace{(d_1^k)_j}_{\check{e}_{2i,2j}^k}$$

(AY)

$$f_{2j}^k = \underbrace{(\mathcal{P}_{k-1}^k f^{k-1})_{2j}}_{(\mathcal{P}_{k-1}^k f^{k-1})_{2j}} + \underbrace{f_j^{k-1} - \xi_j^{k-1} - (d_1^k)_j}_{e_{2j}^k}$$

Strategy (E1) vs Strategy (AY). Algorithm

Inverse transform (E1) 2D

$$\varepsilon = (\varepsilon_k) \text{ and } 0 \leq \kappa \leq 1$$

$$\text{for } k = 1, \dots, L$$

$$\text{for } j = 1, \dots, J_{k-1}$$

$$\hat{\xi}_j^{k-1} = (\mathcal{D}_k^{k-1} \mathcal{P}_{k-1}^k \hat{f}^{k-1})_j$$

$$(d_0^k)_j = \hat{f}_{i,j}^{k-1} - \hat{\xi}_j^{k-1}$$

$$(\hat{d}_0^k)_j = \text{tr}((d_0^k)_j, \kappa \varepsilon_{k-1})$$

$$\hat{f}_{2j-1}^k = (\mathcal{P}_{k-1}^k \hat{f}^{k-1})_{2j-1} + (d_0^k)_j + (\hat{d}_1^k)_j$$

$$\hat{f}_{2j}^k = (\mathcal{P}_{k-1}^k \hat{f}^{k-1})_{2j-1} + (d_0^k)_j - (\hat{d}_1^k)_j$$

Aràndiga and Yáñez (2016): "Non-consistent cell-average MR operators with application to image processing." *Applied Mathematics and Computation*

Strategy (E1) vs Strategy (AY). Algorithm

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Motivation

Amat, Dadourian, Liandrat, Ruiz, Trillo (2010): "On a class of L^1 -stable nonlinear cell-average MR schemes." *Journal of Comput. and Applied Mathematics*

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = f_j^{k-1} + \frac{1}{8}(f_{j-1}^{k-1} - f_{j+1}^{k-1}) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = f_j^{k-1} + \frac{1}{8}(f_{j-1}^{k-1} - f_{j+1}^{k-1}) \end{cases}$$

where $\Delta f_j^k = f_j^k - f_{j-1}^k$ where $M_2(x, y) = \varepsilon_2(x, y) \frac{1}{2}(x + y)$ with

$$\varepsilon_2(x, y) = \left| \frac{\text{sign}(x) + \text{sign}(y)}{2} \right| \left(1 - \left| \frac{x - y}{x + y} \right|^2 \right), \forall x, y \in \mathbb{R} \setminus \{0\};$$

$$\varepsilon_2(x, 0) = 0, \forall x \in \mathbb{R}; \quad \varepsilon_2(0, y) = 0, \forall y \in \mathbb{R}.$$

Serna and Marquina (2004)

Motivation

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$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = f_j^{k-1} - \frac{1}{4} \left(\frac{\Delta f_j^k + \Delta f_{j+1}^k}{2} \right) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = f_j^{k-1} + \frac{1}{4} \left(\frac{\Delta f_j^k + \Delta f_{j+1}^k}{2} \right) \end{cases}$$

where $\Delta f_j^k = f_j^k - f_{j-1}^k$ where $M_2(x, y) = \varepsilon_2(x, y) \frac{1}{2}(x + y)$ with

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$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = f_j^{k-1} - \frac{1}{4} M_2(\Delta f_j^k, \Delta f_{j+1}^k) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = f_j^{k-1} + \frac{1}{4} M_2(\Delta f_j^k, \Delta f_{j+1}^k) \end{cases}$$

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New family of operators

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = f_j^{k-1} + \frac{1}{8}(f_{j-1}^{k-1} - f_{j+1}^{k-1}) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = f_j^{k-1} + \frac{1}{8}(f_{j-1}^{k-1} - f_{j+1}^{k-1}) \end{cases}$$

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New family of operators

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = \frac{3}{4} f_j^{k-1} + \frac{1}{4} f_{j-1}^{k-1} - \frac{1}{4} \left(\frac{\Delta f_{j+1}^k - \Delta f_j^k}{2} \right) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = \frac{3}{4} f_j^{k-1} + \frac{1}{4} f_{j+1}^{k-1} - \frac{1}{4} \left(\frac{\Delta f_{j+1}^k - \Delta f_j^k}{2} \right) \end{cases}$$

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New family of operators

$$\begin{cases} (\mathcal{P}_{k-1}^k f^{k-1})_{2j-1} = \frac{3}{4}f_j^{k-1} + \frac{1}{4}f_{j-1}^{k-1} - \frac{1}{4}D_2(\Delta f_{j+1}^k, \Delta f_j^k) \\ (\mathcal{P}_{k-1}^k f^{k-1})_{2j} = \frac{3}{4}f_j^{k-1} + \frac{1}{4}f_{j+1}^{k-1} - \frac{1}{4}D_2(\Delta f_{j+1}^k, \Delta f_j^k) \end{cases}$$

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$$\varepsilon_2(x, 0) = 0, \forall x \in \mathbb{R}; \quad \varepsilon_2(0, y) = 0, \forall y \in \mathbb{R}.$$

New family of operators: Some properties

Order of approximation

If $S_{\text{WMD}} = \mathcal{P}_{k-1}^k$. For any function $f \in \mathcal{C}^3(\mathbb{R})$, $h > 0$ and $f^0 = \{f(jh)\}_{j \in \mathbb{Z}}$ then

if $\Delta f_{j+1}^{k-1} \Delta f_j^{k-1} > 0$ for all $j = 1, \dots, J_{k-1} - 1$, $k \in \mathbb{N}$,

$$|(S_{\text{WMD}} f^0)_j - f(j\frac{h}{2})| \leq \mathcal{O}(h^3),$$

otherwise

$$|(S_{\text{WMD}} f^0)_j - f(j\frac{h}{2})| \leq \mathcal{O}(h^2),$$

New family of operators: Some properties

Theorem

Harizanov and Oswald (2010): Stability of non-linear and multiscale transforms. Constructive Approximation

Let S_{NL} be a non-linear subdivision scheme defined by:

$$(S_{NL}f)_j = (Sf)_j + F(\delta f)_j,$$

with δ a linear and continuous operator in l^∞ and F a non-linear operator in l^∞ . If S_{NL} , F and δ satisfy that

$$\exists M > 0 \quad : \quad \forall d \in l^\infty \quad \|F(d)\|_\infty \leq M \|d\|_\infty \quad (2)$$

$$\exists L > 0, \exists c < 1 \quad : \quad \forall f \in l^\infty \quad \|\delta S_{NL}^L(f)\|_\infty \leq c \|\delta(f)\|_\infty \quad (3)$$

then the subdivision scheme S_{NL} is convergent.

New family of operators: Some properties

Convergence of the subdivision scheme

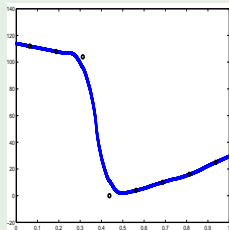
The subdivision scheme S_{WMD} is convergent.

Monotonicity preservation

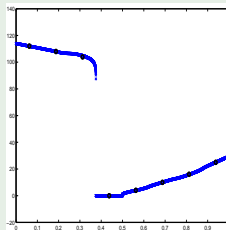
Under certain conditions, the subdivision scheme S_{WMD} preserves the monotony of the points

New family of operators: Some properties

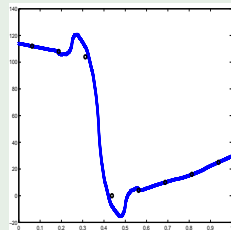
Example $f^0 = (112, 108, 104, 0, 4, 10, 16, 25)$



S_{WMD}



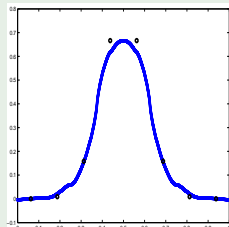
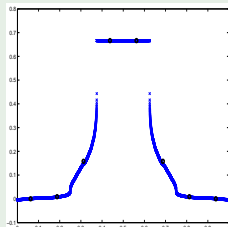
Amat et al.



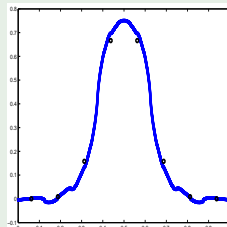
CA

New family of operators: Some properties

Example $y = [-2.1 : 0.6 : 2.1]$ and $f_j^0 = f(y_j)$

 S_{WMD} 

Amat et al.



CA

New family of operators: Some properties of the MR scheme

Stability of the MR scheme

$$\|f^k - \hat{f}^k\|_\infty \leq 2\|f^{k-1} - \hat{f}^{k-1}\|_\infty + \|d_0^k - \hat{d}_0^k\|_\infty + \|d_1^k - \hat{d}_1^k\|_\infty$$

$$\|f^k - \hat{f}^k\|_1 \leq 2\|f^{k-1} - \hat{f}^{k-1}\|_1 + \|d_0^k - \hat{d}_0^k\|_1 + \|d_1^k - \hat{d}_1^k\|_1$$

Order of the MR scheme

The prediction operator, \mathcal{P}_{k-1}^k , reproduces the polynomials of degree 1 in cell-average context.

Some examples

$$(\hat{d}_1^k)_j = \begin{cases} (d_1^k)_j, & \text{if } |(d_1^k)_j| \geq \varepsilon_k; \\ 0, & \text{if } |(d_1^k)_j| < \varepsilon_k; \end{cases}$$

with

$$\varepsilon_{k-1} = \begin{cases} \frac{\varepsilon_k}{2}, & \text{if } \varepsilon_k \geq 1/2; \\ 1/2, & \text{if } \varepsilon_k < 1/2 \end{cases}$$

$$(\hat{d}_0^k)_j = \begin{cases} (d_0^k)_j, & \text{if } |(d_0^k)_j| \geq \kappa \varepsilon_{k-1}; \\ 0, & \text{if } |(d_0^k)_j| < \kappa \varepsilon_{k-1}; \end{cases}$$

with $\kappa = 0.3$.

- PSNR = Peak signal noise ratio \uparrow PSNR \equiv \uparrow quality
- NNZ = Non-zero elements \uparrow NNZ \equiv \downarrow compression

Numerical experiments: Image *lena* with $L = 4$

	$\varepsilon = 8$			$\varepsilon = 16$		
	ℓ_1	PSNR	NNZ	ℓ_1	PSNR	NNZ
CA	3.024	36.10	20085	4.204	32.75	8930
WMD	3.028	36.07	20087	4.195	32.73	8930
PPH	3.108	35.81	20815	4.312	32.40	9303
	$\varepsilon = 32$			$\varepsilon = 40$		
	ℓ_1	PSNR	NNZ	ℓ_1	PSNR	NNZ
CA	5.755	29.58	3616	6.298	28.68	2651
WMD	5.732	29.53	3616	6.285	28.61	2651
PPH	5.865	29.18	3715	6.405	28.31	2745

Numerical experiments: Image *lena* with $L = 4$



Original image

Numerical experiments: Image *lena* with $L = 4$



CA

Numerical experiments: Image *lena* with $L = 4$



WMD

Numerical experiments: Image *lena* with $L = 4$



PPH

Numerical experiments: Image *lena* with $L = 4$



Original image

Numerical experiments: Image *lena* with $L = 4$



CA

Numerical experiments: Image *lena* with $L = 4$



WMD

Numerical experiments: Image *lena* with $L = 4$



PPH

Numerical experiments: Image *barbara* with $L = 4$

	$\varepsilon = 8$			$\varepsilon = 16$		
	ℓ_1	PSNR	NNZ	ℓ_1	PSNR	NNZ
CA	3.482	34.95	49152	5.739	30.16	26454
WMD	3.488	34.92	49153	5.746	30.11	26456
PPH	3.573	34.64	52316	5.955	29.69	27615
	$\varepsilon = 32$			$\varepsilon = 40$		
	ℓ_1	PSNR	NNZ	ℓ_1	PSNR	NNZ
CA	8.857	26.14	10888	10.107	24.96	6968
WMD	8.895	26.07	10888	10.154	24.90	6968
PPH	9.111	25.71	10654	10.308	24.59	6731

Numerical experiments: Image *geopa* with $L = 4$

	$\varepsilon = 8$			$\varepsilon = 16$		
	ℓ_1	PSNR	NNZ	ℓ_1	PSNR	NNZ
CA	0.477	45.37	6685	1.284	38.32	3136
WMD	0.396	45.73	6685	1.093	38.70	3136
PPH	0.117	48.57	3521	0.372	40.97	2149
	$\varepsilon = 32$			$\varepsilon = 40$		
	ℓ_1	PSNR	NNZ	ℓ_1	PSNR	NNZ
CA	2.043	34.83	1679	2.410	33.43	1261
WMD	1.712	35.35	1679	2.081	33.82	1261
PPH	0.713	36.78	1226	0.868	35.38	989

Present work

- Prove the stability in ℓ^2
- Use the schemes in other applications as signal denoising
- Generalize the method using a scheme with a major number of cells
- Introduce properties to generalize the function D_2

Thank you!

Present work

- Prove the stability in ℓ^2
- Use the schemes in other applications as signal denoising
- Generalize the method using a scheme with a major number of cells
- Introduce properties to generalize the function D_2

Thank you!